

Problem Set C1.

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①

$$(A) \Rightarrow (B)$$

$$(B) \Rightarrow (C)$$

This is just integration by parts and using compactness or boundary value.

For example

$$\int_{\Omega} \Delta u \cdot \varphi + \int_{\Omega} \nabla u \cdot \nabla \varphi = \int_{\partial\Omega} \frac{\partial u}{\partial n} \varphi$$

② Existence for (C) : the widest class.

Uniqueness for (A) : the smaller class,

In PDEs we aim at finding some balance between the first and the second.

③

$$(A) \Rightarrow (A^*)$$

If $u \in C^2(\bar{\Omega})$ and $u=0$ on $\partial\Omega$

then trace of u is 0. Then $u \in H^2(\Omega) \cap H_0^1(\Omega)$

$-\Delta u = f$ a.e. follows from $-\Delta u = f$ everywhere

$(B) \Rightarrow (B^*)$ Similar.

(4) $(B^*) \Leftrightarrow (B^{**})$

$(B^*) \quad u \in H_0^1(\Omega), \int_D u \cdot D\varphi = \int f \varphi \quad \forall \varphi \in C_c^\infty$

$(B^{**}) \quad u \in H_0^1(\Omega), \int_D \nabla u \cdot \nabla \psi = \int f \psi \quad \forall \psi \in H_0^1(\Omega).$

If $\varphi \in C_c^\infty \Rightarrow \varphi \in H_0^1(\Omega)$ so $B^{**} \Rightarrow B^*$.

If $\psi \in H_0^1(\Omega)$, there is $\varphi_n \rightarrow \psi$ in $H^1(\Omega)$.

In particular, $\int_D \nabla u \cdot \nabla \varphi_n \rightarrow \int_D \nabla u \cdot \nabla \psi$
 $\int f \varphi_n \rightarrow \int f \psi.$

(5) $u \in H^2(\Omega) \cap H_0^1(\Omega), \int_D \nabla u \cdot \nabla \psi = \int f \psi \quad \forall \psi \in C_c^\infty$

But $\nabla u \in H^1(\Omega)$, $\nabla \psi \in C_c^\infty$. Using def.
of weak der $-\int_D \Delta u \cdot \psi = \int_D f \psi \quad i.e. -\Delta u = f$

⑥

We simply integrate by parts to get

$$\int \nabla u \cdot \nabla \varphi + \int c(x) u \cdot \varphi + \int b(x) \nabla u \cdot \nabla \varphi = 0.$$