

Dynamical systems

Endomorphic Dynamics - iteration of endomorphic maps in $\hat{\mathbb{C}}$

Geometric theory of measure

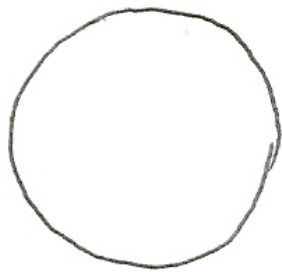
Harmonic measure in the plane

Dynamics in $\mathbb{CP}^k$

Literature:

- "Wstęp do gładkich układów dynamicznych" W. Szlenk
- "I course in dynamical systems", "modern theory of D.S." Katok, Hasselblatt
- Clark Robinson
- F. Przytycki, Urbański (Cambridge)
- Ricardo Mañé "Ergodic theory of D.S."
- Pollett, Yuri (Cambridge)

First example

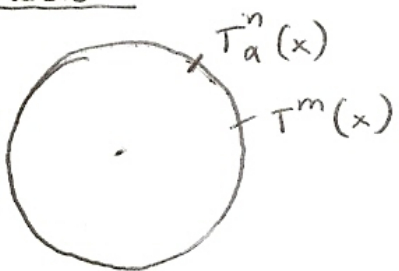


S^1

- T_α - rotation by angle α

Proposition: (1) If $\frac{\alpha}{\pi}$ is rational then every trajectory is finite (periodic)
 (2) If $\frac{\alpha}{\pi}$ is irrational then every trajectory is dense in S^1

Explanation:



Given $\delta = \frac{1}{N}$, there are $n, m \leq N+1$ such that $d(T_\alpha^n x, T_\alpha^m x) < \delta$; (length S^1).

Proposition: For every continuous function $f: S \rightarrow \mathbb{R}$, then

$$(*) \quad \frac{f + f \circ T_\alpha + \dots + f \circ T_\alpha^{n-1}}{n} \implies \int_{S^1} f d\ell \quad \ell - \text{normalized Lebesgue measure on } S^1$$

, where T_α is an irrational rotation.

Proof: $f, f \circ T_\alpha, \dots, f \circ T_\alpha^k, \dots$ sequence of random variables, equally distributed
 $P(f \circ T_\alpha < a) = P(T_\alpha^{-1}(f < a)) = P(f < a)$

(1) Consider f : (trigonometric polynomial) $(**) f(z) = z^k$, check that $(*)$ holds for f .

use density of linear combination of functions $(**)$ in $C(S^1)$.

Corollary: consider the following sequence of measures, $x \in S^1$

$$\mu_n = \frac{\delta_x + \delta_{T_\alpha x} + \dots + \delta_{T_\alpha^{n-1} x}}{n} \xrightarrow{*} \text{Leb}(S^1) \quad \text{normalized}$$

$$\mu_n(f) \rightarrow \text{Leb}(f)$$

~~$\mathbb{Z}_n(\mathbb{F}) \rightarrow \text{Leb}(\mathbb{F})$~~ Def: $T: X \rightarrow X$ continuous, X -compact, metric

T is called topologically transitive if $\forall U, V$ open there exists $n \in \mathbb{N}$ so that $T^n(U) \cap V \neq \emptyset$

Proposition: X -compact, metric, separable space

$T: X \rightarrow X$ continuous map. Then T is topologically transitive $\Leftrightarrow$ there exists a dense orbit.

Proof: " $\Leftarrow$ " obvious

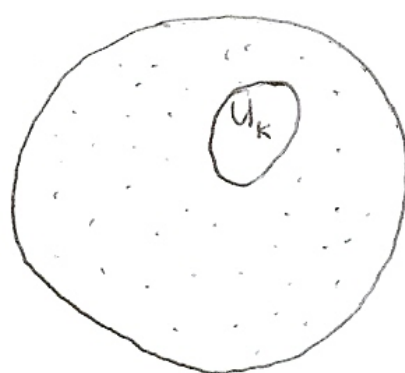
" $\Rightarrow$ " since X is separable there exists a countable basis of topology. $\rightarrow$ countable family of open sets U_k such that $\forall x \in X \quad \forall \epsilon > 0$ there exists $x \in U_k \subset U$.

$$R_k = \{x \in X : \forall n \in \mathbb{N} \quad T^n(x) \notin U_k\}$$

$$R_k \text{ - closed } \bigcap_n T^{-n}(X \setminus U_k)$$

with empty interior

$$\text{int } R_k = \emptyset$$



From Baire's theorem we get $\bigcup_k R_k \neq X$

Generalization to $\mathbb{T}^k$:

$$\mathbb{T}^k = S^1 \times \dots \times S^1$$

$$(z_1, \dots, z_k) \xrightarrow{T} (e^{2\pi i a_1} z_1, e^{2\pi i a_2} z_2, \dots, e^{2\pi i a_k} z_k)$$

Example:

$$\mathbb{T}^2 \quad \left. \begin{array}{l} a_1 \text{ rational, } a_1 = 0 \\ a_2 \text{ irrational} \end{array} \right\} \begin{array}{l} \text{no dense trajectory} \\ \text{no periodic trajectory} \end{array}$$



a_1, a_2 both rational all trajectories are periodic

Proposition: (1) If $(a_1, \dots, a_k)$ are independent over $\mathbb{Z}$

$$\text{i.e. } (*) \quad n_1 a_1 + n_2 a_2 + \dots + n_k a_k \in \mathbb{Z}$$

the only solution of $(*)$ in $\mathbb{Z}$ is $n_1 = n_2 = \dots = n_k = 0$, then every trajectory is dense.

(2) If $a_1, \dots, a_k$ are not independent, then there is no dense trajectory

Proof: $k=2$ a_1, a_2

$$n_1 a_1 + n_2 a_2 \in \mathbb{Z}$$

then we take the function $\varphi(z_1, z_2) = z_1^{n_1} z_2^{n_2}$

$$\varphi \circ T(z_1, z_2) = z_1^{n_1} z_2^{n_2} e^{2\pi i (n_1 a_1 + n_2 a_2)} = z_1^{n_1} z_2^{n_2} \quad \varphi \text{ is } T\text{-invariant}$$

$\Rightarrow T$ is not transitive

25.02.2011

$$f: S^1 \rightarrow S^1$$

continuous, $\deg f = 1$

f monotone



$$S^1 = \mathbb{R}/\mathbb{Z}$$

$$F(x+1) = F(x) + d$$

$$F: \mathbb{R} \rightarrow \mathbb{R}$$

$$F(\mathbb{Z}) \subseteq \mathbb{Z}$$

Def: $f: M \rightarrow M$ orientable manifold, $x \in M$ regular value

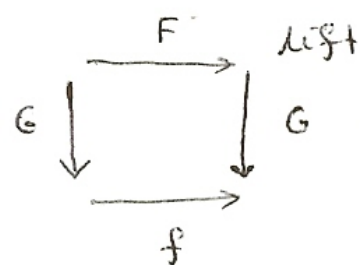
$$\forall f(x)=x \quad Df \text{ invertible}, \quad \deg = \sum_{x \in f^{-1}(x)} \text{sign } f'(x)$$

$$G: \mathbb{R} \rightarrow S^1$$

$$\theta \rightarrow e^{2\pi i \theta}$$

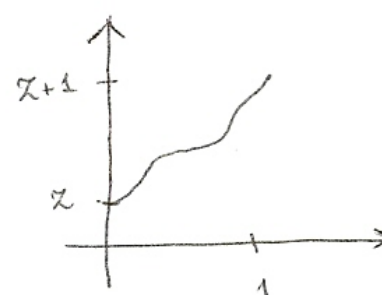
$$\mathbb{R}/\mathbb{Z} \leftrightarrow S^1$$

Fact: $\exists F: \mathbb{R} \rightarrow \mathbb{R} \quad \forall x \quad F(x+1) = F(x) + 1$



commutes

$$\tilde{F} = F + m \quad \text{integer}$$



H. Poincaré

$$g(F) = \lim_{n \rightarrow \infty} \frac{F^n(x)}{n} \quad - \text{rotation number (wreath abrotu)}$$

Theorem 1: $g(F)$ exists, does not depend on x

$$\text{Example: } f_\alpha(x) = x + \alpha \pmod{1}$$

$$f_\alpha(x) = x \cdot e^{2\pi i \alpha}, \quad |x|=1$$

$$g(f_\alpha) = \alpha$$

Simple properties: $F(x+m) = F(x) + m$

$$F+k : g(F+k) = g(F) + k$$

F monotone, increasing

Proof of thm 1:

$$\forall q \quad \exists p \quad q, p \geq 0 \quad \text{integers}$$

$$p \leq F^q(0) \leq p+1$$

$$F^{2q} \leq F^q(0) + p+1 \leq 2(p+1)$$

?

$$F^{nq}(0) \leq n(p+1), \quad F^{nq}(0) \geq np$$

$$\frac{p}{q} \leq \frac{1}{nq} F^{nq}(0) \leq \frac{p+1}{q}$$

$$\frac{p}{q} \leq \liminf_{n \rightarrow \infty} \frac{F^{nq}(0)}{nq} \leq \limsup_{n \rightarrow \infty} \dots \leq \frac{p+1}{q}$$

$$nq+r, \quad 0 \leq r < q$$

$$\frac{p}{q} \leq \liminf_k \frac{F^k(0)}{k} \leq \limsup_k \frac{F^k(0)}{k} \leq \frac{p+L}{q}$$

$$q \text{ - arbitrary so } \forall q \quad (\limsup - \liminf) \leq \frac{1}{q}$$

so $\lim$ exists. Does not ~~ex~~ depend on x , $0 \leq x \leq y \leq 1$

$$\begin{array}{c} g(F, 0) \leq g(F, x) \leq g(F, y) \leq g(F, 1) \\ \parallel \qquad \qquad \qquad \parallel \\ g(F) \qquad \qquad \qquad g(F) \end{array}$$

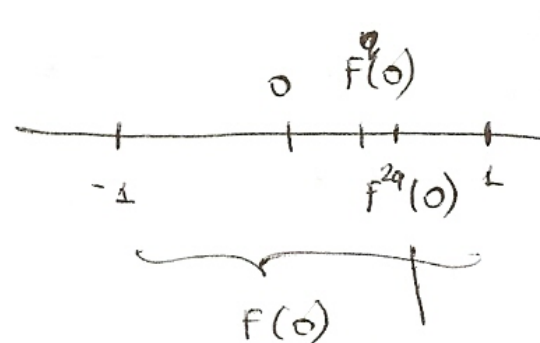
Theorem 2:

$$g(F) \in \mathbb{Q} \iff \exists \text{ a periodic point for } f$$

$$\exists q, x \quad f^q(x) = x, \quad F^q(x) = x + p$$

Proof:

" $\Rightarrow$ " for simplicity let's assume that $g(F) = 0$, $q g(F) = \frac{p}{q} - \text{ex.}$



$$F^{(n+1)q}(0) - F^{nq}(0) \rightarrow 0$$

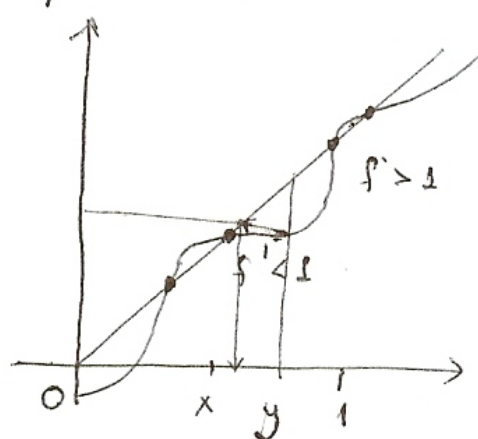


$$F^q(x) = x$$

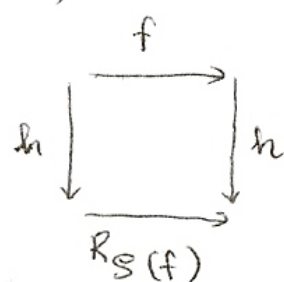
it won't be smaller than 1 then $\exists$ a fixed point for F

$$F^q(x) - p = 0$$

$$g(F) = \frac{p}{q}$$



Theorem(3): There exists $\exists h: \mathbb{S}^1 \rightarrow \mathbb{S}^1$, continuous, monotone, $\deg h = 1$
 $R_\alpha(x) = x + \alpha \pmod{1}$ $\forall f$ - monotone, $f: \mathbb{S}^1 \rightarrow \mathbb{S}^1$, $\deg 1$, continuous, $g(f) \notin \mathbb{Q}$



h is called semiconjugacy

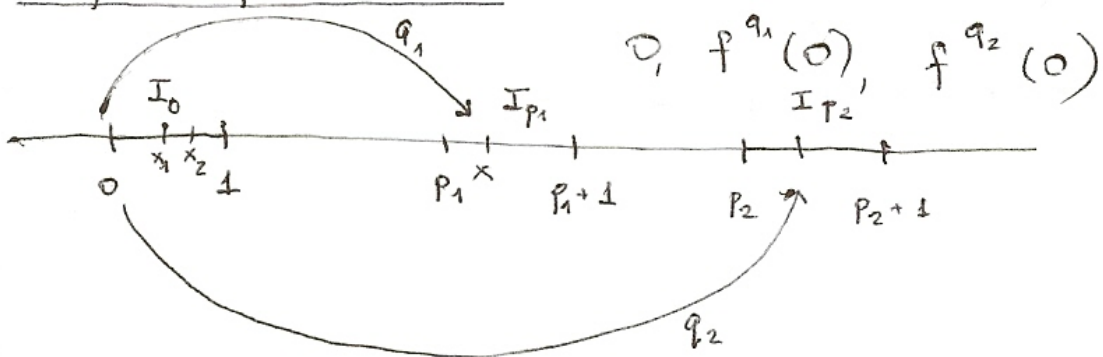
Theorem 4: If f is diffeomorphism, $\text{var } \log |f'| < \infty$, then h is homeo (h from thm 3).

Remark: $C^2 \Rightarrow f'$ Lipschitz

How smooth h is

Flow smooth h is
 $|g(t) - p/q| \geq \frac{c}{q^m}$ diophantine condition

Proof of thm 3:



deg is preserved

$$F^{q_2 - q_1}(x) \geq p_2 - p_1$$

define h on any trajectory $0, f(0), \dots \rightarrow 0, g(t), 2g(t), 3g(t), \dots$
 monotone

$$f^{q_{n+1}}(x) \times f^{q_n}(x)$$

4.03.2011

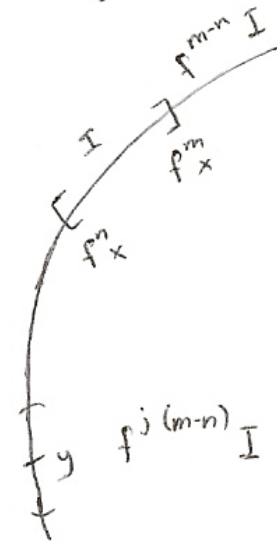
Twierdzenie (Denjoy): Jeżeli $f: S^1 \rightarrow S^1$ jest zachowującym orientację dyfeomorfizmem klasy C^2 (a nawet wystarczy mniej tzn ze $\log|f'|$ ma ograniczone wahanie) $\times$ niewymierną liczbą obrotu ρ , to f jest topologicznie sprzężone z obrotem R_ρ

$$\begin{array}{ccc} S^1 & \xrightarrow{f} & S^1 \\ h \downarrow & & \downarrow h \\ S^1 & \xrightarrow{R_\rho} & S^1 \end{array}$$

Lemać: Niech f będzie zachowującym orientację homeomorfizmem okręgu

$z \in S(f) \notin \mathbb{Q}$, $x \in S^1$ $I = [f^n x, f^m x]$ dla pewnych $n, m \in \mathbb{Z}$

wówczas $\forall y \in S^1 \exists k \in \mathbb{Z}$ t.ze $f^k y \in I$.



D: Rozpatrzmy $I, f^{m-n}(I), f^{2(m-n)}(I), \dots$

albo $\bigcup_{j \in \mathbb{Z}} f^{j(m-n)} I = S^1$

wtedy dobrze

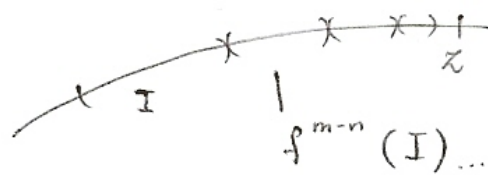
albo $\bigcup \neq S^1$

$$\text{wówczas } z = \lim_j f^{j(m-n)}(f^n x) \Rightarrow f^{(m-n)}(z) = z$$

$$\tilde{f} := f^{(m-n)}$$

$$\lim_j \tilde{f}^j v = z$$

sprzeczności z niewymiernością $\rho(f)$.



Stwierdzenie: f - zachowujący orientację homeomorfizm okręgu, $\rho(f) \notin \mathbb{Q}$, to

(a) $\omega(x)$ nie zależy od x

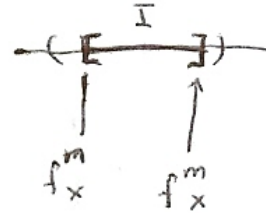
(b) $\omega(x) = S^1$ albo $\omega(x)$ jest doskonałym, niezdegenerowanym, domkniętym podzbiorem S^1 .

(c) (ogólne prawda) $\omega(x)$ jest f -niezmienniczy

$$f(\omega(x)) = f^{-1}(\omega(x)) = \omega(x)$$

Dowód: (c) jasne

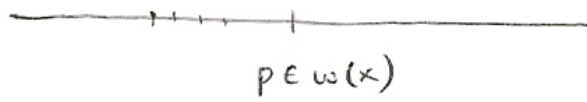
(b) jeżeli $\text{int}(\omega(x)) \neq \emptyset$



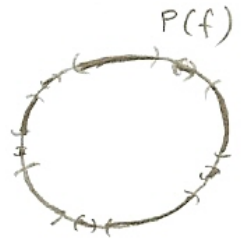
powtarzając argument z poprzedniego lematu dostajemy, że w tym przypadku $\omega(x) = S^1$.

Doskonałość tj. brak punktów izolowanych

$$\omega(x) = \omega(p) \ni f^{n_i}(p) \rightarrow p$$

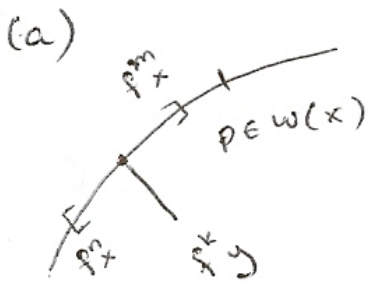


Jak znaleźć ciąg punktów $q_i \in \omega(x)$ $q_i \rightarrow p$



$$(a) \Rightarrow \omega(x) = \omega(p)$$

$f^{n_i}(p) \rightarrow p$ z niezmienniczości $f^{n_i}(p) \in \omega(p) = \omega(x)$. wskazałismy więc punktów zb. do p .



weźmy dowolne $y \in S^1$. Pokazujemy, że $p \in \omega(y)$ wówczas istnieje $k \in \mathbb{N}$ t. że $f^k(y) \in [f_x^k, f_x^m]$ (z lematu)

zatem istnieje ciąg $f^{k_i} y \rightarrow p$.

Stwierdzenie: Jeżeli I jest składając do dopełnienia $J(f) = S^1 \setminus P(f)$

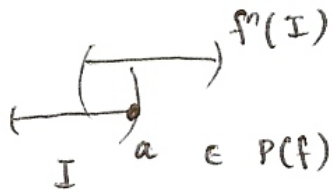
to I jest odunkiem błądzącym (wandering)

$$\text{tzn } f^n(I) \cap I = \emptyset \quad \forall n \in \mathbb{Z}$$

$\Downarrow$

$$f^n(I) \cap f^m(I) = \emptyset \quad n \neq m$$

Dowód:



a: koniec $I \cap a \in P(f)$
Jeżeli $f^n(I) \cap I \neq \emptyset$ to $a \in f^n(I)$, ale również $f^n(I)$ jest rozłączone z $P(f)$.

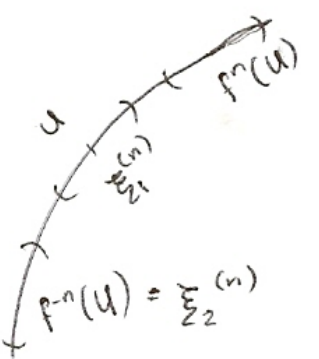


Stwierdzenie: (główny krok w dowodzie Denjoy)

Jeżeli f spełnia założenia tw. Denjoy, to $P(f) = S^1$

Dowód: Jeżeli $P(f) \neq S^1$ to istnieje odunek $u \in S^1 \setminus P(f)$

(niech u będzie składając $S^1 \setminus P(f)$)

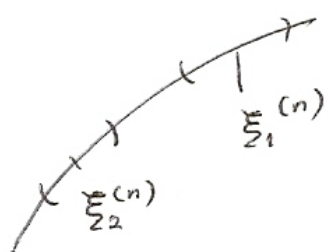


$$\frac{|f^n(u)|}{|u|} = |(f^n)'|(\xi_1^{(n)}) \quad \text{dla pewnego } \xi_1^{(n)} \in u$$

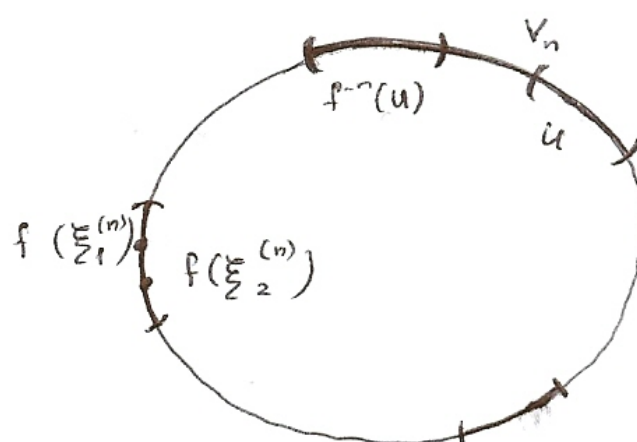
$$\frac{|f^{-n}(u)|}{|u|} = \frac{1}{|(f^n)'|(\xi_2^{(n)})} \quad \text{dla pewnego } \xi_2^{(n)} \in f^{-n}(u)$$

$$\left| \log \frac{|f^n(u)| \cdot |f^{-n}(u)|}{|u|^2} \right| = \left| \log \frac{|(f^n)'(\xi_1^{(n)})|}{|(f^n)'(\xi_2^{(n)})|} \right| = \left| \log \frac{\prod_{j=0}^{n-1} |(f')(\xi_j^{(n)})|}{\prod_{j=0}^{n-1} |(f')(\xi_j^{(n)})|} \right| =$$

$$= \left| \sum_{j=0}^{n-1} (\log |(f')(\xi_j^{(n)})| - \log |(f')(\xi_j^{(n)})|) \right| \quad (*)$$



Pokażemy, że istnieje nieskończenie wiele takich, że tu będzie $\xi_1^{(n)}, \xi_2^{(n)}$



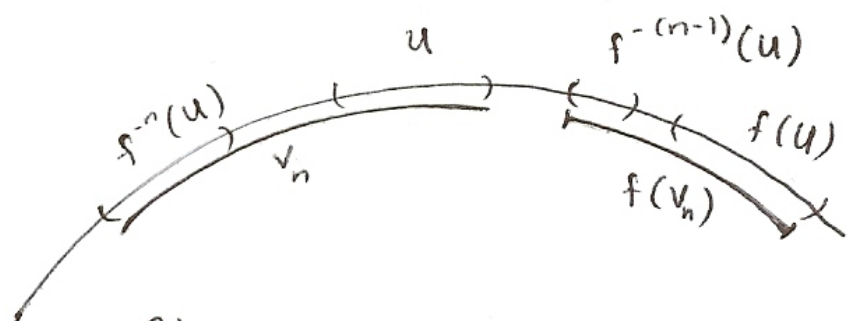
$$\xi_1^{(n)} \in U$$

mają rozłączne drogi f^j dla $j=0, 1, \dots, n-1$

$$\xi_2^{(n)} \in f^{-n}(U)$$

stąd będzie wynikało, że (*) jest ograniczone przez stałą (nieskończone wahanie $\log f'$)

Tymczasem (*) jest nieograniczone przy $n \rightarrow \infty$. Stąd sprzeczność.

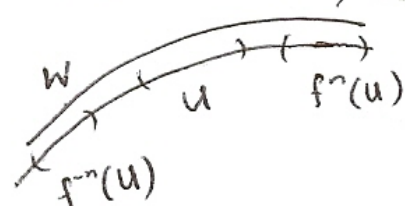


Pokażemy, że $V_n, f(V_n), \dots, f^{n-1}(V_n)$ są rozłączne (jeśli n wybierzemy odpowiednio) nie może wpasnąć do V_n

Wówczas będziemy mieli $f(V_n) \cap V_n = \emptyset$

$f^2(V_n)$ musimy założyć, żeby było rozłączne z $V_n, f(V_n)$

Warunek wystarczający na to, żeby były parami rozłączne



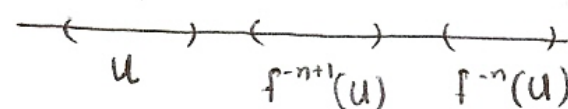
adunka $V_n, f(V_n), \dots, f^{n-1}(V_n) \quad (*)$

w tym tu nie może być wcześniejszych obrazów $f^j(V_n)$ dla $|j| < n$.

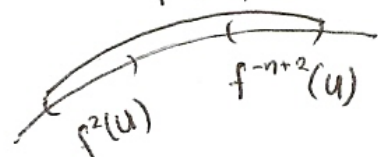
11.03.2011

End of the proof of Denjoy theorem

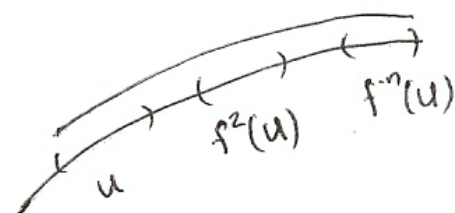
If $f(V_n) \cap V_n \neq \emptyset \Rightarrow f^{-n+1}(u)$ falls in V_n



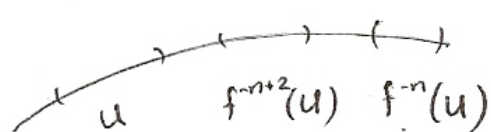
$$f^2(V_n) \cap V_n = \emptyset$$



If $f^2(V_n) \cap V_n \neq \emptyset$ then either $f^2(u) \cap V_n \neq \emptyset$ or $f^{-n+2}(u) \cap V_n \neq \emptyset$



or



In order to verify (*) we need to choose n so that

$\left. \begin{array}{l} f(u), f^2(u), \dots, f^{n-1}(u) \\ f^{-n+1}(u), f^{-n+2}(u), \dots, f^{-1}(u) \end{array} \right\}$ do not intersect $V_n \quad (**)$

Let us consider the rotation $T_g, g = g(f)$

choose n such that $d(T_g^n x, x) < d(x, T^j x)$
for all $1 \leq j < n-1$

$\Rightarrow d(T_g^{-n} x, x) = d(T_g^n x, x) < d(x, T_g^j x) = d(x, T_g^{-j} x)$

If n is chosen like this then the $(*)$ is satisfied since $(***)$ implies that $(**)$ is satisfied.

Why $(***) \Rightarrow (**) ?$ we have a semiconjugacy

$$\begin{array}{ccc} S^1 & \xrightarrow{f} & S^1 \\ \downarrow h & & \downarrow h \\ S^1 & \xrightarrow{T_g} & S^1 \end{array}$$

Choose an arbitrary point $z \in U$, denote $x \in h(z)$ the order of points $x, f^1(x), f^2(x), \dots$ in S^1 is the same as the order of points $T^j(x)$

$$g(f) \in \mathbb{Q}$$

Def: $f: S^1 \rightarrow S^1$ a C^1 -diffeomorphism preserving orientation is called Morse-Smale diffeomorphism if

$$(1) \quad g(f) \in \mathbb{Q}$$

(2) all periodic points are non-degenerated (if $f^q(p) = p$ then

$$|f^q(p)'| \neq 1)$$

(equivalently if F is a lift and $F^q(x) = x + p, (F^q)'(x) \neq 1$

$$\begin{array}{ccc} x & \mathbb{R} & \xrightarrow{F} & \mathbb{R} \\ \downarrow \pi & & & \downarrow \pi \\ x & S^1 & \xrightarrow{f} & S^1 \end{array}$$

Def: Let f be a C^1 -diffeomorphism preserving orientation.

f is C^1 -structurally stable if there is a C^1 -neighbourhood U of f such that for every $\tilde{f} \in U$ is topologically conjugate to f .

$$\begin{array}{ccc} S^1 & \xrightarrow{f} & S^1 \\ h \downarrow & & \downarrow h \\ S^1 & \xrightarrow{\tilde{f}} & S^1 \end{array} \quad h\text{-homeo}$$

Exercise: verify that diff are open in C^1 -topology

Theorem: C^1 -diffeomorphism $f: S^1 \rightarrow S^1$ (preserving orientation) is C^1 -structurally stable if f is M-S diffeomorphism. Moreover: C^2 -M-S are C^2 -dense in the space of C^2 orientation preserving diffeomorphisms $S^1 \rightarrow S^1$.

Corollary: since every C^1 -diffeomorphism $f: S^1 \rightarrow S^1$ can be C^1 -approximated by C^2 -diffeomorphisms, this implies that M-S diff are C^1 -dense in the space $\text{diff}^1(S^1)$.

Proof: First we prove that if f is H -S C^1 -diffeomorphism then

f is C^1 -structurally stable.

Let $g(f) = \frac{p}{q}$. First we replace f by $g = f^q$, then $g(g) = 0$ and there is a lift G of g such that the only points x satisfying $G^n x = x + m$ (for some m, n) are fixed

points $x_1, \dots, x_N = x_1 + 1$.

Given $\exists \varepsilon > 0$ s.t.

one can find neighbourhoods $U_i \ni x_i$ so that

$$(1) |G(x) - x| > \varepsilon \quad x \notin U_i$$

$$(2) |G'(x) - 1| > \varepsilon \quad \text{in } U_i$$

There, $\exists$ exists δ so that if $\tilde{f}$ is δ - C^1 close to f then there exists a lift $\tilde{F}$ of $\tilde{f}$ which is C^1 -close to F and a lift $\tilde{G}$ of $\tilde{f}^q$ ($\tilde{G} = \tilde{F}^q + p$) which is $\frac{\varepsilon}{2}$ - C^1 -close to G for some integer

then observe that

$$(1) |\tilde{G}'(x) - 1| > \frac{\varepsilon}{2} \quad \text{on } \bigcup U_i$$

(2) At the end points of U_i 's the graph of $\tilde{G}$ is on the same side of the diagonal as G

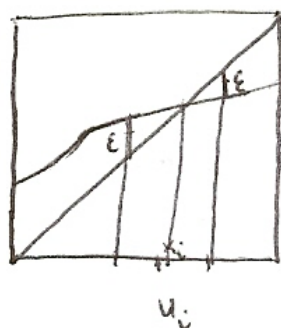
$$(3) |\tilde{G}(x) - x| > \frac{\varepsilon}{2} \quad \text{outside } \bigcup U_i$$

(1) $\rightarrow$ (3) implies that $\tilde{G}$ has exactly one fixed point

in each U_i

$$\tilde{G}(x) - x = 0$$

$$\tilde{G}'(x) - 1 \neq 0 \quad \text{in } U_i$$

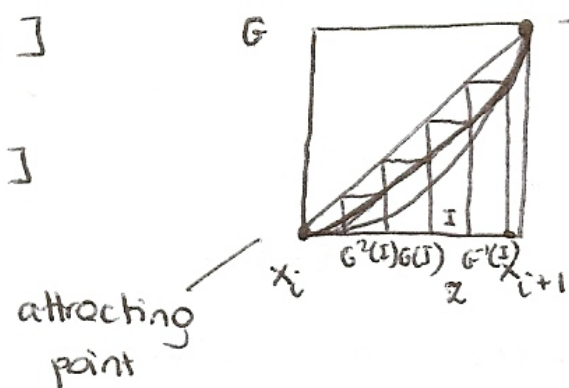


Let $\tilde{x}_1, \dots, \tilde{x}_N$ be fixed points of $\tilde{G}$

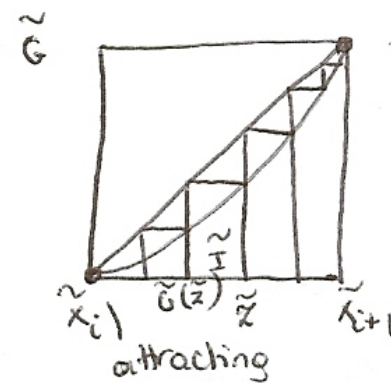
How to construct the conjugacy between G and $\tilde{G}$ on the intervals $[x_i, x_{i+1}]$

$$\downarrow$$

$$[\tilde{x}_i, \tilde{x}_{i+1}]$$



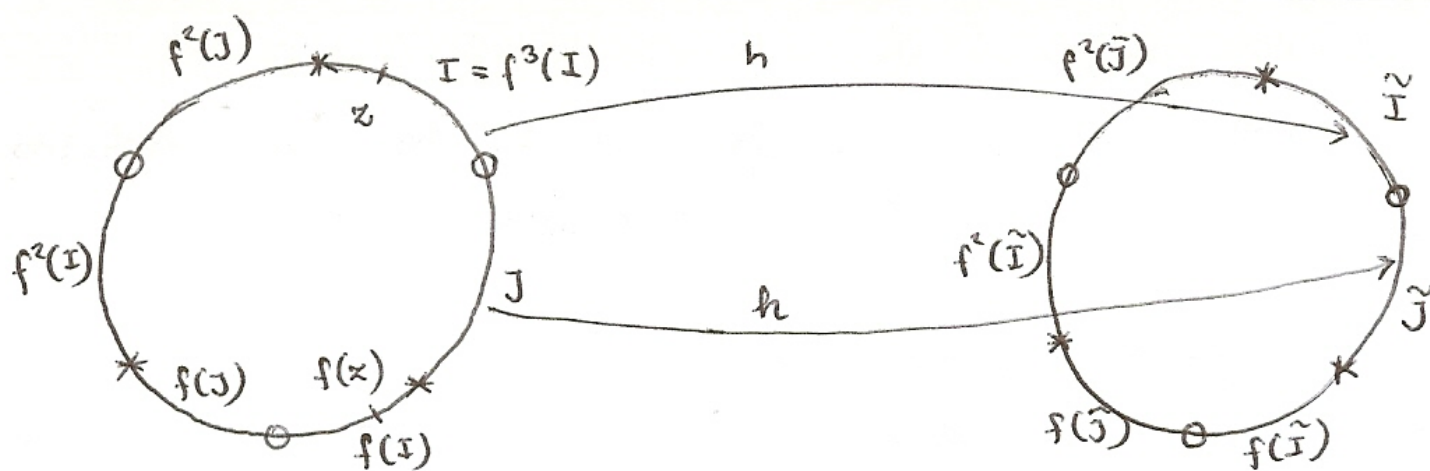
repeating point



repeating

$h_i: I \rightarrow \tilde{I}$ an arbitrary homeomorphism (preserving orientation)

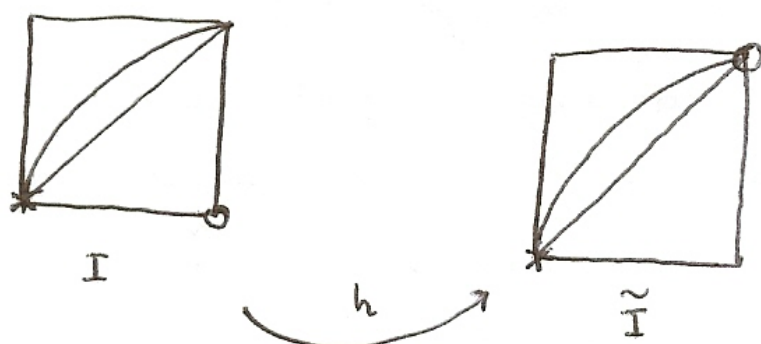
$$h(G^j(w)) = \tilde{G}^j(h(w))$$



f has 2 periodic orbits of period (3)

* repelling
o attracting

Graph of $f^3|_I$
(or rather it's lift $\tilde{g}$)



we construct the conjugacy $h: I \rightarrow \tilde{I}$ as before

How to define h on $f(I)$? we have to put

$$h(f(x)) = \tilde{f}(h(x)), \quad x \in I$$

Similarly we define h on $f^2(I)$ putting $h(f^2(x)) = \tilde{f}^2(h(x))$

Final observation h is a conjugacy between f and $\tilde{f}$

similarly on $f(J), f^2(J)$

This is a conjugacy between f and $\tilde{f}$ because we have to put $h(f^3(x)) = \tilde{f}^3(h(x))$ (*) at the points $f^3(x)$ ($x \in I$)

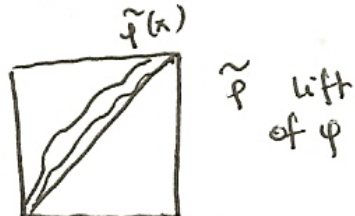
But h was already defined on I , since h was a conjugacy between f^3 and $\tilde{f}^3$ on I , this means that

(*) is satisfied for h which we started with

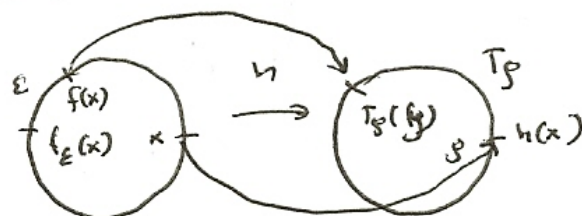
18.03.2011 "=>"

step 2 given f - C^2 diffeo with $g(f)$ irrational. How to check

that f is not C^1 stable?



$\tilde{f}$ lift of f



$$f_\varepsilon = T_\varepsilon \circ f$$

by Denjoy thm: $h \circ f_\varepsilon \circ h^{-1} = \varphi \circ T_\varepsilon$
conjugate of f_ε

Conclusion: $\varphi(f_\varepsilon) \neq g(f)$

step 3: Therefore f_ε is not topologically conjugate to f . f -arbitrary C^1 diffeo with $g(f) \notin \mathbb{Q}$?
Assume that f is C^1 -structurally stable. Then $\exists u, \exists f$ in C^1 -topology $\approx$ that every $g \in V$ $g \approx f$, in particular $g(g) = g(f)$. But C^2 -diffeo are dense in C^1 -topology. One can choose $g \in V$ s.t. $g \in C^2$. See previous figure g can be perturbed to $g_\varepsilon \approx g$ so that $g(g) \neq g(g_\varepsilon)$

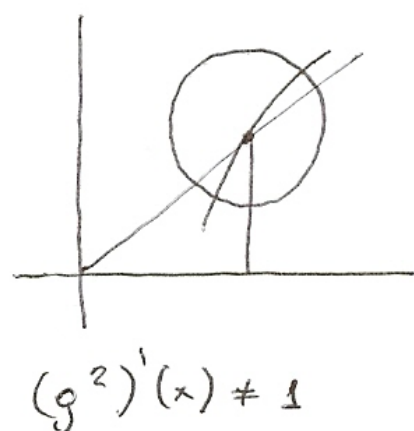
~~1/2~~ ~~5/4~~ ~~dx/dt~~ ~~dx/dt~~

Step 4 density of H-S diff in C^1 -topology. Let f be an arbitrary C^1 diff. Let $U \ni f$ be an arbitrary neighbourhood of f .

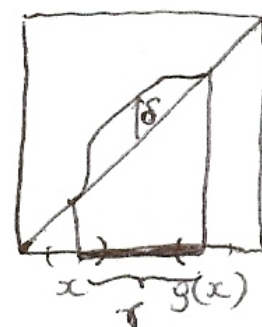
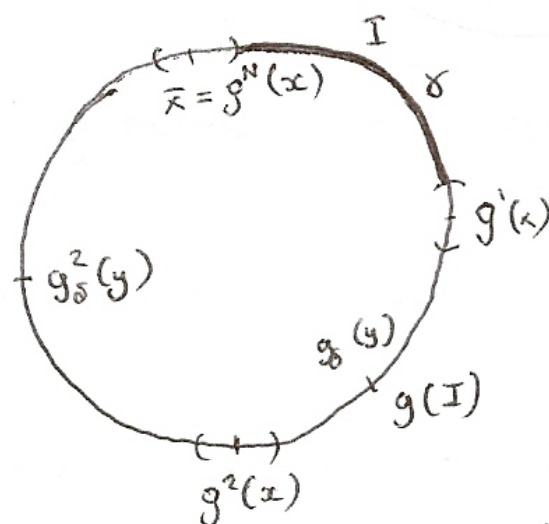
First we find C^2 diff $g \in U$. Either $g(q) \in \mathbb{Q}$ or $g(q) \notin \mathbb{Q}$. If $g(q) \notin \mathbb{Q}$ then again we consider g_ε as before

$$\varepsilon \rightarrow g_\varepsilon \rightarrow \begin{matrix} S(g_\varepsilon) \\ \text{rational} \end{matrix} \quad S(g)$$

If all periodic orbits of g_ε are non-degenerated then g_ε is H-S, if not, then we choose one periodic orbit and we perturb g_ε slightly in C^1 -topology so that this point x remains periodic and becomes non-degenerated



Call this perturbed map



Let $k: S' \rightarrow S'$ be defined
 $k = \text{id}$ outside γ
 $k = \text{as in the picture}$ on γ

$$S(g) = \frac{p}{q}$$

Now, every periodic orbit of g has period q (in the picture, $q=3$) and it crosses the arc γ , y -period point in (γ)

$$\begin{array}{ccc} G: \mathbb{R} & \longrightarrow & \mathbb{R} \\ \downarrow & & \downarrow \\ y: S' & \longrightarrow & S' \end{array}$$

$$G^q(Y) = Y + p$$

Y is periodic for G

$$G_\delta^q(Y) = Y + p + \delta$$

g_δ is a perturbation of g

$$g_\delta = k_\delta \circ g$$

If Y is so that $y = \tau(Y) \in \gamma$ then (1) y is periodic for g iff

$$G^q(Y) = Y + p$$

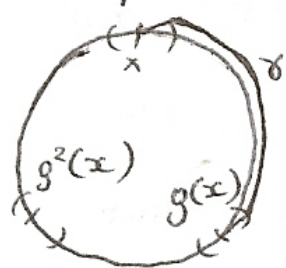
(2) y is periodic for g_δ iff

$$G^q(Y) = Y + p + \delta$$

we want all periodic ~~points~~ orbits of g_δ to be non-degenerated $y \neq x$

$$G_\delta^q(Y) = Y + p + \delta$$

$$\text{and } (G_\delta^q)'(Y) \neq 1$$



Let $L(Y) = G^q(Y) - Y$

We see that $y = \pi(Y)$ is a degenerate periodic point of G_δ iff

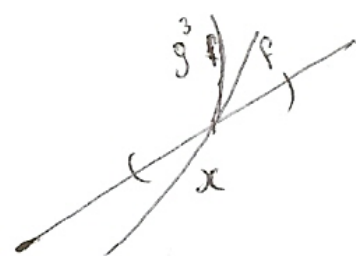
$L(Y) = \delta + p$ and $L'(Y) = 0$

Conclusion: If δ is chosen so that $p + \delta$ is not a critical value of L , then the map G_δ has no degenerate periodic orbits, i.e. G_δ is a M-S diffeomorphism.

We need Sard's lemma

Lemma: If $f: [0, 1] \rightarrow \mathbb{R}$ is a C^2 map then $\text{Leb}(\text{critical values of } f) = 0$

$\Rightarrow G_\delta$ has no degenerate periodic orbits in γ



x - fixed point of f
 $f'(x) \neq 1$

Then there exists a neighbourhood $V \ni x$ and $\delta > 0$ so that if f_δ is a C^1 -perturbation of f , f_δ is C^1 close to f then f_δ has only one fixed point in V

To finish the proof we need to know that if f is C^1 -str. stable $\Rightarrow f$ is M-S. We know already

- (1) If f is str. stable then $g(f) \in \mathbb{Q}$
- (2) If f is stable then f has finitely many periodic orbits

- (3) If one of these periodic points is degenerate then one can perturb f in C^1 -topology so that the number of periodic points changes

$\Rightarrow f$ cannot be struct-stable

25.03.2011

dimension 2

Diff of π^2

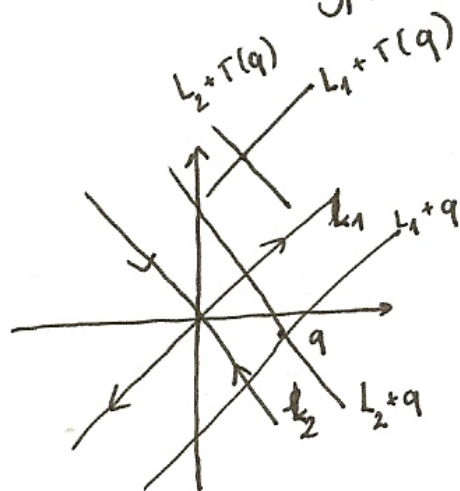
Example: (important)

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ linear map, ex of a linear hyperbolic automorphism of $\mathbb{R}^2$

$T(x) = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} x$

$\lambda_1 = \frac{3+\sqrt{5}}{2} > 1$ $\lambda_2 = \frac{3-\sqrt{5}}{2} < 1$

$y = \frac{\sqrt{5}-1}{2} x$ $y = -\frac{\sqrt{5}+1}{2} x$



$$T(\mathbb{Z}^2) = \mathbb{Z}^2$$

$$\det T = 1$$

$$T^{-1} = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$$

T induces a diffeomorphism $\pi^2 \ni$

$$f = \pi \circ T \circ \pi^{-1}$$

$$T(L_1 + q) = L_1 + T(q)$$

$$\begin{array}{ccc} \mathbb{R}^2 & \xrightarrow{T} & \mathbb{R}^2 \\ \pi \downarrow & & \downarrow \pi \\ \pi^2 & \xrightarrow{f} & \pi^2 \end{array}$$

$$\pi^2 = \mathbb{R}^2 / \mathbb{Z}^2$$

Def: Let $f: M \ni$ diff C^1 , a fixed point p ($f(p) = p$) is called hyperbolic iff $\text{spec}(D_p f: T_p M \ni)$ does not contain eigenvalues of mod 1.

Ex: Point $(0,0)$ is a hyperbolic fixed point of T

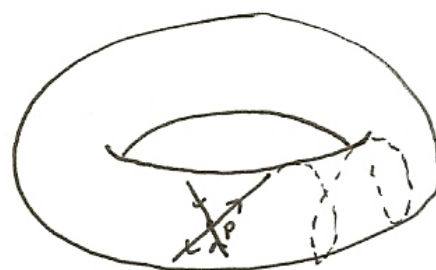
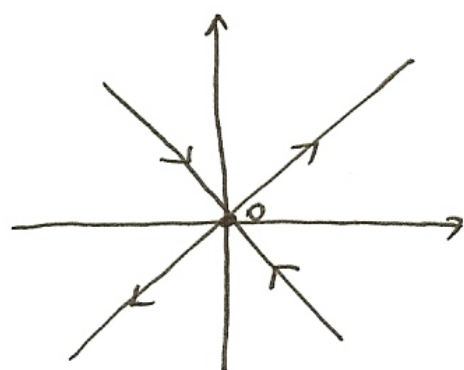
Def: If p - periodic, with period n then is hyperbolic if $D_p f^n: T_p M \ni$ has no eigenvalues of mod 1

Def: f is a diffeomorphism of a smooth manifold M , $M \subset \mathbb{R}^n$. Let $\Lambda \subset M$ be a ~~compact~~ ^{closed} f -invariant subset. we say that Λ is a hyperbolic set if for every $p \in \Lambda$ there is a splitting $T_p M = E_p^s \oplus E_p^u$ so that

$$(1) \quad D_p f(E_p^s) = E_{f(p)}^s$$

$$(2) \quad D_p f(E_p^u) = E_{f(p)}^u$$

and $\exists c > 0, \lambda > 1$ so that $\forall p \in \Lambda$, $\|D_p f^n(v)\| \leq c \lambda^{-n} \|v\|$, $v \in E_p^s$
 $\|D_p f^{-n}(v)\| \leq c \lambda^n \|v\|$, $v \in E_p^u$



$$D_0 \psi(L_1) = E_p^u$$

$$D_0 \psi(L_2) = E_p^s$$

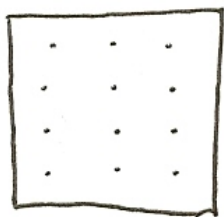
(not H-S system)

$$\psi(L_1) = W^u(p, f) - \text{unstable manifold of } p$$

$$\psi(L_2) = W^s(p, f) - \text{stable manifold of } p$$

Proposition: f induced by T (from example) on π^2 $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$
 f has a dense subset of periodic orbits

Proof:



fundamental square

consider the set

$$Q = \left(\frac{m_1}{n}, \frac{m_2}{n} \right) \in \mathbb{R}^2$$

$$\text{then } T(Q) = \left(\frac{\tilde{m}_1}{n}, \frac{\tilde{m}_2}{n} \right)$$

Thus the trajectory of $q = \pi(Q)$, $q \in \mathbb{T}^2$ is finite

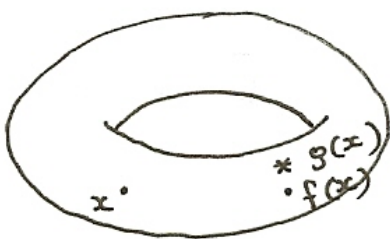
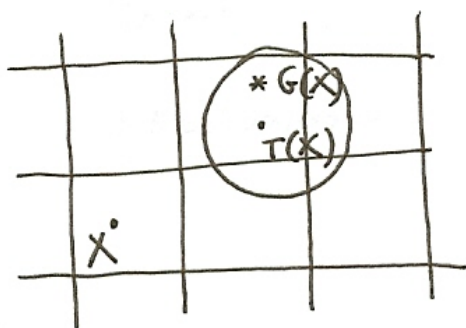
These are all periodic points if $x \in \mathbb{T}^2$ periodic

$$\begin{array}{c} X \\ \downarrow \pi \\ x \end{array} \quad T^n(X) = X + \underbrace{(m, n)}_{\mathbb{Z}^2}$$

$$(T^n - I)(X) \in \mathbb{Z}^2 \Rightarrow X = (T^n - I)^{-1}(m, n)$$

Theorem: The diff f (induced by T) is C^1 -structurally stable

Proof: Let $g: \mathbb{T}^2 \rightarrow \mathbb{T}^2$ be a diffeomorphism which is C^1 -close to f . We claim that there exists a map $G: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which is C^1 -close to T such that $\pi \circ G = g \circ \pi$, locally $G = \pi^{-1} \circ g \circ \pi$



G is a small C^1 -perturbation of T

We refer to Grobman-Hartman theorem (on local stability)

Thm: (1) (version for diff)

Let f be a C^1 diffeomorphism defined in a neighbourhood of 0 (in $\mathbb{R}^n$). $f(0) = 0$, 0 is a hyperbolic fixed point.

Let $L = D_0 f$

Then $\exists U \ni 0$ in $\mathbb{R}^n$ and a homeomorphism H , $H(0) = 0$

and $H: U \rightarrow H(U)$

$$\begin{array}{ccc} U & \xrightarrow{f} & U \\ h \downarrow & & \downarrow \\ h(U) & \xrightarrow{L} & L(H(U)) \end{array} \quad H \circ f = L \circ H$$

(2) (version for ~~flows~~ flows)

Let X be a C^1 vector field defined in a neighbourhood of 0 (in $\mathbb{R}^n$). $X(0) = 0$, assume that $A = D_0 X$ has no eigenvalues λ with $\operatorname{Re} \lambda = 0$. Then $\exists U \ni 0$, and a homeomorphism H on U so that

$$\begin{array}{ccc} U & \xrightarrow{\varphi_t} & U \\ H \downarrow & & \downarrow H \\ U & \xrightarrow{\psi_t} & U \end{array} \quad \begin{array}{l} \varphi_t - \text{flow on the field } X \\ \psi_t - \text{flow defined by } \dot{x} = Ax \end{array}$$

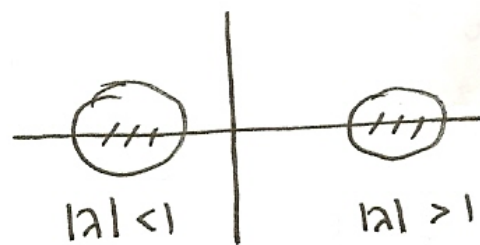
$$\psi_t(x) = \exp(tA)(x)$$

Outline of proof of G-H thm:

Lemma 1: Let L be hyperbolic, linear automorphism $L: \mathbb{R}^n \rightarrow \mathbb{R}^n$, then there exists a norm in $\mathbb{R}^n$ so that

$$\|L|_{E^s}\| < a < 1$$

$$\|L^{-1}|_{E^u}\| < a < 1$$



$$\mathbb{R}^n = E^s \oplus E^u$$

Lemma 2: Let B be a Banach space. Let

$\mathcal{L}: V \rightarrow V$ linear operator so that $\|\mathcal{L}\| < a < 1$. Let G be an invertible linear operator so that

$$\|G^{-1}\| < a < 1 \quad \text{then}$$

(a) $I + \mathcal{L}$ is invertible and $\|(I + \mathcal{L})^{-1}\| \leq \frac{1}{1-a}$

(b) $I + G$ is invertible and $\|(I + G)^{-1}\| \leq \frac{a}{1-a}$

Proof: exercise

Proposition: Let L be a linear hyperbolic automorphism in $\mathbb{R}^n$. Then $\exists \varepsilon > 0$ such that if $\varphi \in C_b(\mathbb{R}^n)$ ($\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^n$) and φ is Lipschitz continuous with constant $\leq \varepsilon$ then L and $L + \varphi$ are topologically conjugate in $\mathbb{R}^n$.

Proof of prop:

We search for $H = I + u$, $u \in C_b(\mathbb{R}^n)$

$$(I + u) \circ L = (L + \varphi)(I + u) \quad \text{continuous, bounded}$$

$$L + u \circ L = L + L \circ u + \varphi(I + u)$$

$$u \circ L - L \circ u = \varphi(I + u)$$

Let $\mathcal{L}: C_b(\mathbb{R}^n) \rightarrow C_b(\mathbb{R}^n)$ be defined as

$$\mathcal{L}(u) = u \circ L - L \circ u$$

Lemma 3: $\mathcal{L}$ is invertible, $\|\mathcal{L}^{-1}\| \leq \frac{\|L^{-1}\|}{1-a}$

(a- was defined in lemma 1, the proof of this lemma refers to lemma 2)

we search for u satisfying $u = \overbrace{\mathcal{L}^{-1}}^{\psi}(\varphi(I + u))$

observation: the map $\psi: C_b(\mathbb{R}^n) \rightarrow C_b(\mathbb{R}^n)$ is a contraction if ε was small

proof of observation: u_1, u_2

$$\|\psi(u_1) - \psi(u_2)\| \leq \|\mathcal{L}^{-1}\| \|\varphi(I + u_1) - \varphi(I + u_2)\| \leq \varepsilon \|u_1 - u_2\|_{\infty} \|\mathcal{L}^{-1}\|$$

01.04.2011

Proof (finish): $g \approx f$, $\mathbb{R}^2$, $G \approx T$ C' close

$G = T + \varphi$, $\varphi - C'$ close to 0 (in particular Lipschitz continuous with L constant $< \varepsilon$)

We have to check that $\exists \varepsilon > 0$ so that $f \approx g$ (ε -close in C^1 -topology)

then $\exists \pi^2 \hookrightarrow \text{homeo}$

$$\begin{array}{ccc} \pi^2 & \xrightarrow{f} & \pi^2 \\ h \downarrow & & \downarrow h \\ \pi^2 & \xrightarrow{g} & \pi^2 \end{array}$$

proof the same as G-H thm

Proof of G-H thm. Main step: $L + \varphi$

$$H = I + u, \quad \underbrace{(I+u)}_H \circ L = (L + \varphi)(I+u) \quad (*)$$

We have found $u \in C_b(\mathbb{R}^m \rightarrow \mathbb{R}^m)$ which satisfies $(*)$. How to check that H is homeo?

Actually, instead of $(*)$, one could have proved $(**)$
 $\exists \varepsilon > 0$ so that if φ_1, φ_2 are ε -close to 0 in $C_b(\mathbb{R}^m \rightarrow \mathbb{R}^m)$
 then there exists a unique solution of $(I+u) \circ (L + \varphi_1) = (L + \varphi_2)(I+u)$

How to check that H is homeo?

Using $(**)$ we produce a unique $v \in C_b(\mathbb{R}^m \hookrightarrow \mathbb{R}^m)$
 satisfying $(I+v) \circ (L + \varphi) = L(I+v)$
 $(I+u)(I+v) = I$

so we have $(I+u)(I+v) = I$, we use uniqueness of solution
 similarly $(I+v)(I+u) = I$, we use uniqueness of solution

3 lemmas used in the proof

- 1st
- 2nd

Lemma 3

$$L: C_b(\mathbb{R}^m) \rightarrow C_b(\mathbb{R}^m)$$

$$L(u) = u \circ L - L \circ u \quad \text{is invertible} \quad \mathbb{R}^n = E^s \oplus E^u$$

Proof:

$$C_b(\mathbb{R}^m \rightarrow \mathbb{R}^m) = C_b^s \oplus C_b^u \quad \text{hyperbolic, linear operator}$$

$$\text{so } u = u^s + u^u$$

We can show L preserves both C_b^s, C_b^u
 invertible on both of them

$$L|_{C_b^s} = L(L^{-1} \circ u \circ L - u)$$

$$L|_{C_b^u} = L(L^{-1} \circ u \circ L - u) - (I - L^{-1} \circ (\cdot) \circ L)$$

$u \mapsto L^{-1} \circ u \circ L$ - contraction in C_b^u
 $I + \text{sth of small norm}$ is invertible

L is contraction here

The proof of proposition is finished. we have proved that if $L: \mathbb{R}^n \hookrightarrow \mathbb{R}^n$
 is a hyperbolic linear operator then there exists $\varepsilon > 0$ such that

in $\varphi: \mathbb{R}^m \rightarrow \mathbb{R}^m$ $\varphi \in C_b(\cdot)$ and $\text{Lip}(\varphi) < \varepsilon$, then there exist
 a homeomorphism $H: H \circ L = (L + \varphi) \circ H$

We used the proposition to finish the proof of a structural
 stability of a hyperbolic automorphism of π^2 $f: \pi^2 \hookrightarrow$

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\begin{array}{ccccccc} \mathbb{R}^2 & \xrightarrow{L} & \mathbb{R}^2 & \xrightleftharpoons{H} & \mathbb{R}^2 & \xrightarrow{G} & \mathbb{R}^2 \\ \downarrow & & \downarrow & & \downarrow & & \downarrow \\ \mathbb{T}^2 & \xrightarrow{f} & \mathbb{T}^2 & \xrightleftharpoons{h} & \mathbb{T}^2 & \xrightarrow{g} & \mathbb{T}^2 \end{array}$$

$$G = L + \varphi$$

The proposition gives us a homeomorphism $H: G \circ H = H \circ L$

Observation: If $H = I + u$ and u is doubly periodic (i.e.) $u(x+p, y+q) = u(x, y)$ $p, q \in \mathbb{Z}^2$ then H gives a homeomorphism $h: \mathbb{T}^2 \rightarrow \mathbb{T}^2$
 $h = \pi \circ H \circ \pi^{-1}$

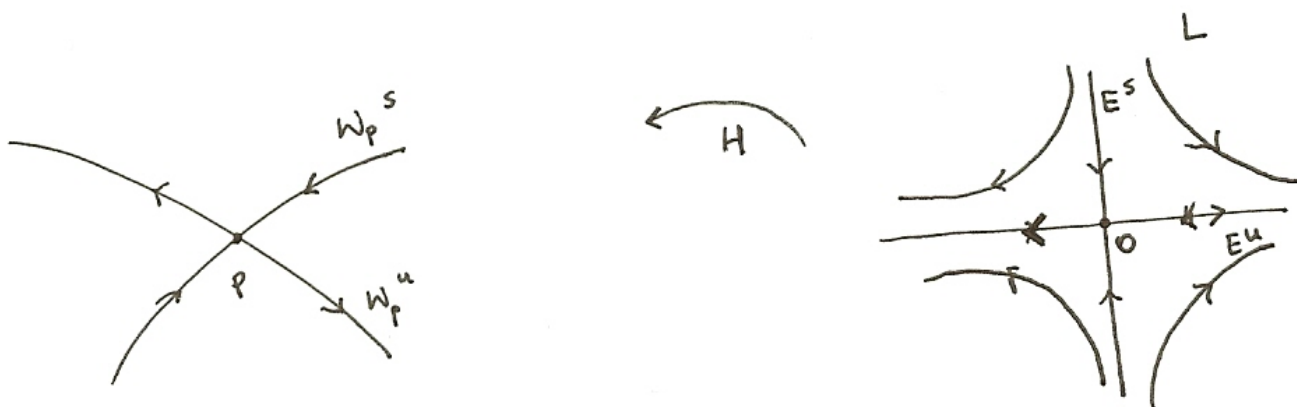
Lemma: If $G = L + \varphi$ and φ is doubly periodic then the solution u of the equation

$$(I + u) \circ L = (L + \varphi) \circ (I + u) \quad \text{is also doubly periodic}$$

This follows from the fact that the operator

$$\mathcal{L}: C_b(\mathbb{R}^m) \rightarrow C_b(\mathbb{R}^m)$$

preserves the subspace of $C_b^{dp}(\mathbb{R}^2 \rightarrow \mathbb{R}^2)$ doubly periodic



Theorem: F -diffeomorphism C^r in neighbourhood of 0 in $\mathbb{R}^n$, $F(0) = 0$, $DF(0) = L$ hyperbolic linear map automorphism. Then there exists $\beta > 0$ such that $W_\beta^s(0) = \{x: \forall n, f^n(x) \in \beta B_\beta(0)\}$

$$W_\beta^u(0) = \{x: \forall n, f^{-n}(x) \in \beta B_\beta(0)\}$$

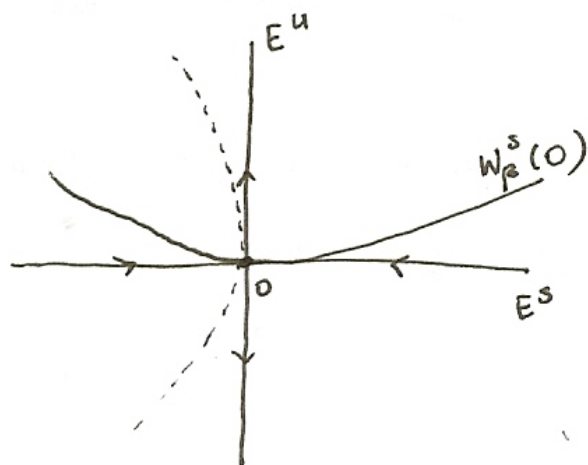
are C^r regular submanifolds of $B_\beta(0)$. Moreover $T_0(W_\beta^s(0)) = E^s$

$$T_0(W_\beta^u(0)) = E^u$$

Generalization: If $F: M \rightarrow M$ is a diffeomorphism of a smooth manifold and p is a hyperbolic fixed point, then the same holds for

$$W_\beta^s(p), W_\beta^u(p)$$

Proof:



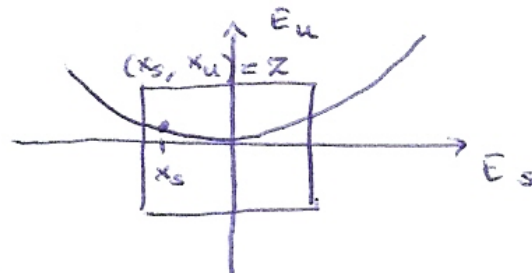
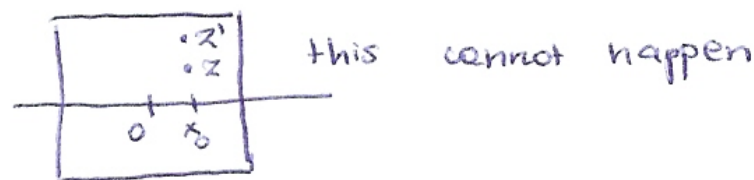
8.04.2011

Hadamard-Perron theorem

Proof (without details)

Lemma 1: If $z = (x_s, x_u) \in B_\beta(0)$ and $z' = (x_s, x_u') \in B_\beta(0)$

and both z, z' are in $W_\beta^s(0)$ then $z = z'$



Our propose: given x_s ($x_s \approx 0$), to find x_u so that the point $z = (x_s, x_u) \in W_\beta^s(0)$

we introduce the space

$$K = \{ \gamma(n) : n \geq 0 : \gamma(n) \in \mathbb{R}^m : \gamma(n) \rightarrow 0 \text{ as } n \rightarrow \infty \}$$

$$\| \gamma(n) \| = \sup_n \| \gamma(n) \|_{\mathbb{R}^m}$$

Proposition: (left as an exercise) K is complete so it is a Banach space.

Let $G \subset K = \{ \gamma(n) : \text{such that } \gamma(n) \in B_\beta(0) \text{ for all } n \}$

Given a point $z \in W_\beta^s(0)$, we can take the sequence $\gamma(n) = F^n(z) \in K$

Then

$$\begin{aligned} \gamma(n) &= F^n(z) = (D+f)^n(z) = (D+f) \circ \underbrace{(D+f)^{n-1}(z)}_{\gamma(n-1)} = D((D+f)^{n-1}(z)) + f(\gamma(n-1)) \\ &= D((D+f)(D+f)^{n-2}(z)) + f(\gamma(n-1)) = \underbrace{D^2((D+f)^{n-2}(z))}_{\gamma(n-2)} + D(f(\gamma(n-2)) + f(\gamma(n-1))) \\ &= \dots = D^n(z) + \sum_{i=0}^{n-1} D^{n-i-1} f(\gamma(i)) \end{aligned}$$

D preserves E^u and E^s

$$\gamma(n) = \gamma^u(n) + \gamma^s(n)$$

$$z = z_u + z_s$$

$$(*) \quad \gamma^u(n) = (D^u)^n(z_u) + \sum_{i=0}^{n-1} D^{n-i-1} f^u(\gamma(i)) = (D^u)^n(z_u + \sum_{i=0}^{n-1} (D^u)^{-i-1} (f^u(\gamma(i))))$$

$$f = f^u + f^s$$

Remember that $\gamma(n) = \gamma^s(n) + \gamma^u(n)$ is a trajectory

of a point $z \in W_\beta^s(0) \Rightarrow$ both $\gamma^s(n)$ and $\gamma^u(n)$ must ~~tend~~ be bounded as $n \rightarrow \infty$. This implies that

$$z_u = - \sum_{i=0}^{\infty} (D^u)^{-i-1} (f^u(\gamma(i))) = \gamma^u(0) \quad (**)$$

Putting it into (*) we get the formula for $\gamma^u(n)$

$$\gamma^u(n) = - \sum_{i=n}^{\infty} (D^u)^{n-i-1} f^u(\gamma(i)) \quad (***)$$

$$\gamma^s(n) = (D^s)^n(\tilde{z}) + \sum_{i=0}^{n-1} (D^s)^{n-i-1} f^s(\gamma(i)) \quad (****)$$

Now we define a map $G: B_\beta^s \times G \rightarrow K$

$$G(x, \gamma)(n) = \gamma(n) - [(* * * *), (* * *)] =: \tilde{\gamma}(n)$$

$$\left. \begin{matrix} \text{in} \\ B_\beta^s \end{matrix} \right|_{g \in K} = \gamma(n) - \left[(D^s(x))^n + \sum_{i=0}^{n-1} D^{n-i-1} f^s(\gamma(i)), - \sum_{i=n}^{\infty} (D^u)^{n-i-1} f^u(\gamma(i)) \right]$$

Strategy: to solve the equation $G(x, \gamma) = 0$ and to verify that

if $G(x, \gamma) = 0$ $\gamma(n)$ is a trajectory $F^n(z)$ of some point

$z = (x, x_u)$ and $z \in W_\beta^s(0)$

$$\tilde{\gamma}(n) \xrightarrow{n \rightarrow \infty} 0$$

we claim that the function $G(x, \gamma)$ is C^1 -smooth

we shall calculate

$$\frac{\partial G}{\partial \gamma}(x, \gamma)(u)(n)$$

$u(n) \in K$

$$\frac{\partial G}{\partial \gamma}(x, \gamma)(u)(n) = u(n) - \left[\sum (D^s)^{n-i-1} df^s(\gamma(i))(u(i)), - \sum_{i=n}^{\infty} (D^u)^{n-i-1} df^u(\gamma(i))(u(i)) \right]$$

$$\frac{\partial G}{\partial \gamma}(0, 0)(u(n)) = u(n)$$

we conclude that there exists a C^1 map (defined in a ngbn of 0 in E^s)

$x \xrightarrow{\varphi} (\gamma(n))(x)$ such that

$$G(x, \varphi(x)) = 0$$

In particular, we have $\gamma(0) = [x, - \sum_{i=0}^{\infty} (D^u)^{n-i-1} f^u(\gamma(i))]$

$$(x, \gamma^u(0)) \in B_\beta^s(0)$$

Define a function h as a composition

$$x \xrightarrow{C^1} \varphi(x) \xrightarrow[\text{projection onto "0" coordinate}]{\text{"} \gamma(n) \text{"}} \gamma(0) \xrightarrow[\text{projection onto } E^u \text{ coordinate}]{\pi_2} (\gamma(0))^u$$

$\xrightarrow{C^1}$

$$(x, h(x)) \in W_\beta^s$$

$$D_x h : E^s \rightarrow E^u$$

$$G(x, \varphi(x))$$

$$\partial_x G + \partial_\gamma G \circ \partial_x \varphi = 0$$

$$\partial_x \varphi = -[\partial_\gamma G]^{-1} \circ \partial_x G$$

$$\frac{\partial G}{\partial x}(0, 0)(v) = (v, D^s(v), \overset{id}{(D^u)^2(v)}, \dots)$$

$$\frac{\partial G}{\partial x}(0, 0)(v)(n) = [(D^s)^n(v), 0] \xrightarrow{D^s} [v, 0] \xrightarrow{\pi_2} 0$$

15.04.2011

Complement of the proof of G-H theorem

we have proved it for diffeomorphisms defined in a neighbourhood of 0. $F = L + f$, L - hyperbolic

Usually G-H is formulated for flows

(*) $x' = g(x)$, $g(0) = 0$, $Dg(0) = A$ has no eigenvalues with $\operatorname{Re} \lambda = 0$

φ_t flow of (*) is conjugate to the linear flow $\dot{x} = Ax$ in some neighbourhood of 0.

Proof for flows: This follows from the proof for diff:

we modify g to $\tilde{g}$ so that

$$\tilde{g} = \begin{cases} g & \text{in a small neighbourhood of } 0 \\ A & \text{outside a larger neighbourhood of } 0 \end{cases}$$

Let $\tilde{\varphi}_t$ be a flow for $\tilde{g}$

$\tilde{\varphi}_t$ is the globally defined (for all t) (follows from Gronwall inequality)

Using the proven part of G-H, we have

Proposition: There exists a homeo H

we expect that this homeomorphism H conjugates in the whole flows, i.e. $\tilde{\varphi}_t \circ H = H \circ e^{At}$

why?

Fix t and consider the new homeomorphism $H_t = \tilde{\varphi}_t \circ e^{-At}$

Then (check!) H_t also conjugates - satisfies (*)

Thus if we check that H_t has a form $H_t = I + u$, (***)

$u \in C_b(\mathbb{R}^n)$ the uniqueness of the conjugacy (see the proof of G-H for diff) will imply $H_t = H$, $\tilde{\varphi}_t \circ H \circ e^{-At} = H$

$$(H_t - I) = \tilde{\varphi}_t \circ H \circ e^{-At} - e^{At} \cdot e^{-At} = \underbrace{(\tilde{\varphi}_t - e^{At}) \circ H \circ e^{-At}}_{\text{bounded}} + \underbrace{e^{At}(H - I)e^{-At}}_{\text{bounded}}$$

t -fixed

Conclusion: $H_t = I + u$, u -bounded. (***) are checked

To finish the proof we have to check that the assumptions of G-H thm (for diff) are satisfied for $\tilde{\varphi}^t$

(to formulate the Proposition)

Pani polewa suitu Bacha na widonczelg.

$$\frac{d}{dt} \tilde{\varphi}^t(x) = \underbrace{(A + \tilde{r})}_{\tilde{g}} \tilde{\varphi}^t(x) \quad \dot{x} = \tilde{g}(x)$$

$$\frac{d}{dt} (e^{-At} \tilde{\varphi}^t(x)) = -A e^{-At} \tilde{\varphi}^t(x) + e^{-At} (A + \tilde{r}) \tilde{\varphi}^t(x) = e^{-At} \tilde{r} \tilde{\varphi}^t(x)$$

$$\text{so } e^{-At} \tilde{\varphi}^t(x) = \int_0^t e^{-As} \tilde{r}(\tilde{\varphi}^s(x)) ds + x$$

$$\tilde{\varphi}^t(x) = e^{At} x + \int_0^t e^{A(t-s)} \tilde{r}(\tilde{\varphi}^s(x)) ds$$

$$\tilde{\varphi}^1(x) = e^A x + \int_0^1 e^{A(1-s)} \tilde{r}(\tilde{\varphi}^s(x)) ds$$

$F = Lx + f$ f has a small Lipschitz constant (?)

$$\tilde{r}(\tilde{\varphi}^1(x)) - \tilde{r}(\tilde{\varphi}^1(x')) \leq (\text{Lip}) \cdot \|\tilde{\varphi}^1(x) - \tilde{\varphi}^1(x')\| \leq C \cdot \|x - x'\|$$

Def: Global stable (unstable) manifold of a hyperbolic fixed point

$$W_p^s(f) = \{x: f^n(x) \rightarrow p\} \quad f: M \rightarrow M \text{ at least } C^1 \text{ diff}$$

$$= \bigcup_{n \geq 0} f^{-n}(W_{p, \text{loc}}^s)$$

Def': For flows X - C^1 -vector fields of M , $\dot{x} = X(x)$ diff. eq.

related to this field, p -stationary, hyperbolic point

($X(p) = 0$ (it implies that p is a fixed, hyperbolic point of φ^t))

$$W_p^s(X) = \{x: \varphi^t(x) \rightarrow p\}$$

Proposition: $W_p^s(\varphi^1) = W_p^s(\varphi^t)$

Proposition (Exercises): $W_p^s(f)$ ($W_p^s(X)$) is an immersed submanifold (of the same class C^r as f (X))

Def: If γ -periodic orbit γ of a flow X then γ is called hyperbolic if $D\varphi^T(x)$ has only one (simple) eigenvalue with modulus $\neq 1$

Def: If γ is a hyperbolic, periodic orbit then

$$W_\gamma^s = \{x: \omega(\{\varphi^t(x)\}) = \gamma\}$$

Picture (Ω -explosion) but first

Def: $\Omega(f)$

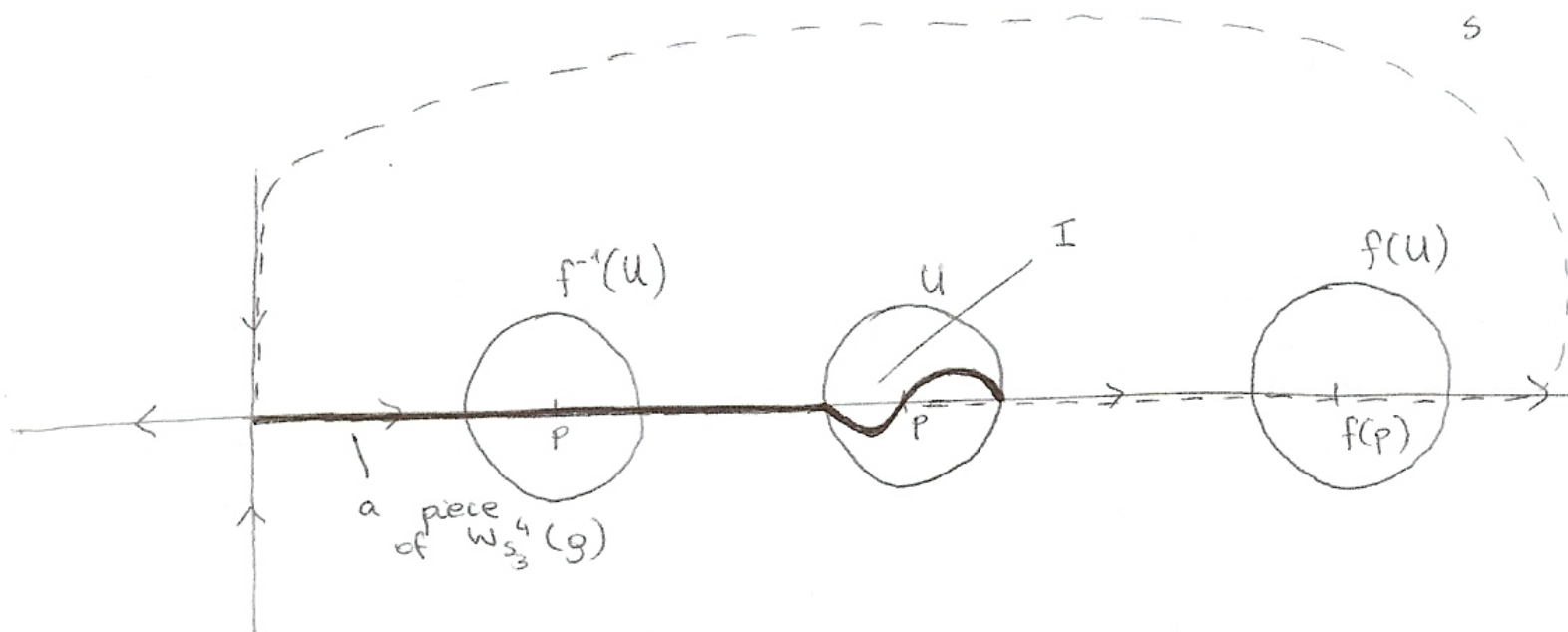
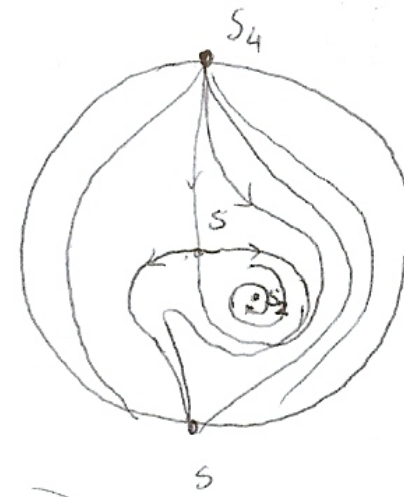
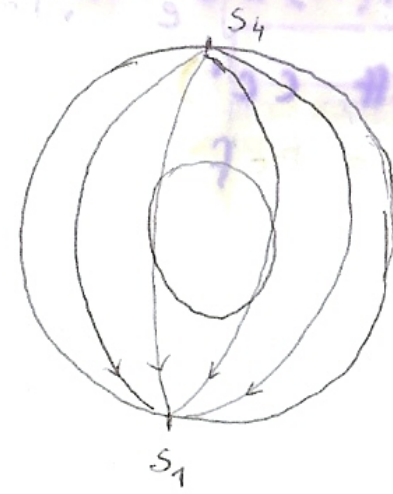
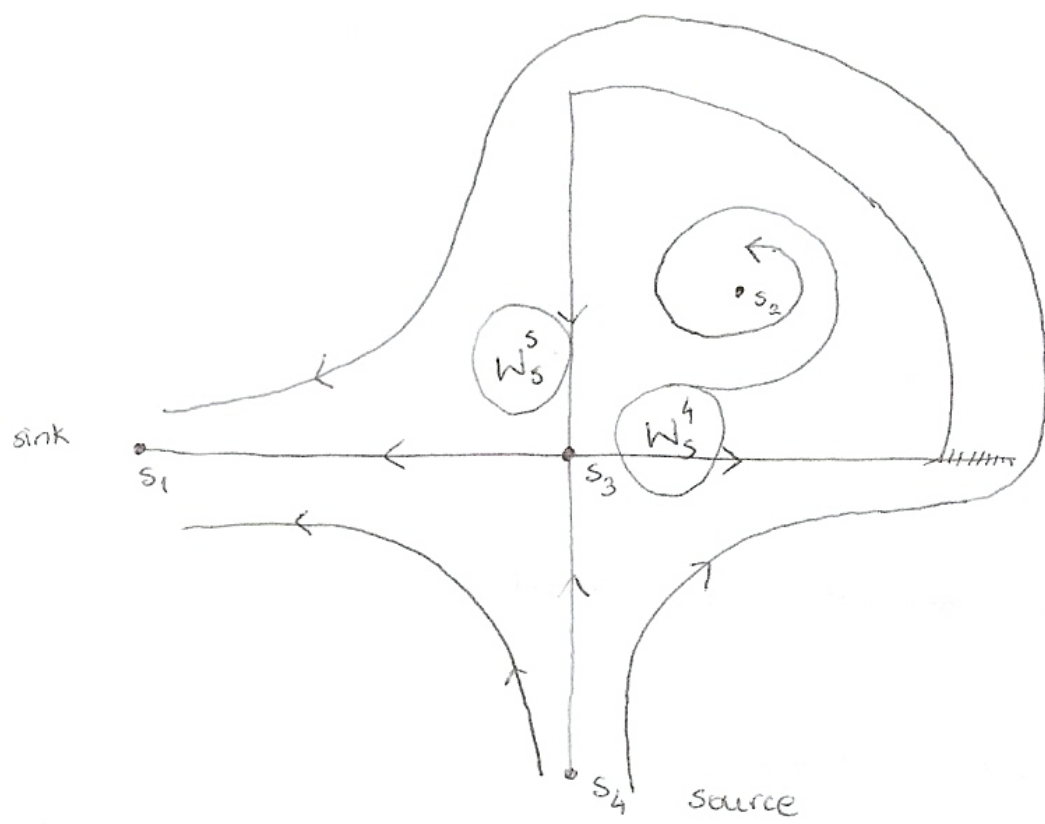
$\Omega(x)$ x flow

wondering point for a flow: x is wondering if $\exists t_0$ and a neighbourhood

$U \ni \bar{x}$ such that

$$\varphi^t(\bar{x}) \cap U = \emptyset$$

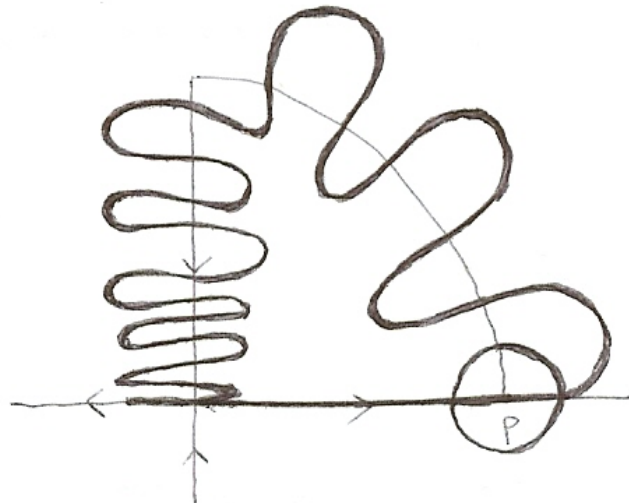
for all $|t| > t_0$



Let i be defined so that $i = \text{id}$ outside U
 we modify f (only locally) and $i(I) =$ 
 we put

$$g = i \circ f$$

$$W_{s_3}^4(g), W_{s_3}^s(g)$$



29.04.2011

Morse Smale systems:

(we know what it means for diffeos on S^1 and we know that M-S diff S^1 form an open set, dense subset and these are the only structurally stable diff S^1)

Definition:

$f: M \rightarrow \mathbb{R}$ diff (C^1) is Morse - Smale iff

- 1) $\Omega(f) = \text{Per } f$
- 2) $\# \text{Per } f < \infty$
- 3) all periodic points are hyperbolic
- 4) $W^s(p) \cap W^u(q)$ intersect transversally (or not at all)

Def:

X - vector field on a compact, smooth manifold M .

φ^t - flow of X .

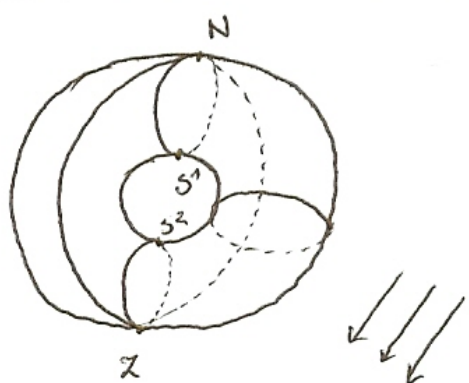
X is called Morse - Smale vector field iff

- 1) $\Omega(X)$ is a union of finite number of stationary points ($X=0$) or periodic orbits.
- 2) all these points and orbits are hyperbolic (called critical elements)
- 3) If σ_1, σ_2 are critical elements then $W^s(\sigma_1), W^u(\sigma_2)$ intersect transversally.

If γ is a periodic orbit then $W^s(\gamma) = \{y: w(y)=\gamma\}$

Theorem: This is an immersed C^1 manifold

Example 1: Consider torus; $h(x) = -x$, $X = \text{grad } h$.



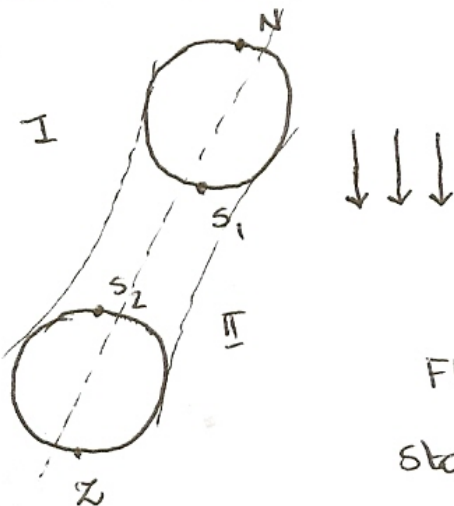
$$v \in T_p M: Dh(v) = \langle \text{grad}_M h, v \rangle$$

$\text{grad}_M h$ = orthogonal projection of $\text{grad } h$ to $T_p M$

No M-S system - two saddles connect (stable and unstable don't intersect transversally)

Example 2:

"lean" the torus. Look at section of this torus.



If the flow starts from part II it remains in part II

There is no more connection between $W^u(s_1)$ and $W^s(s_2)$.

Flow from example 1 is not structurally stable, because after a small perturbation the connection between saddles s_1, s_2 disappeared.

Flow from example 2 is M-S flow.

Theorem: $M-S$ diffeomorphism from an open set in $\text{Diff}(M)$.

Every $M-S$ diff is structurally stable.

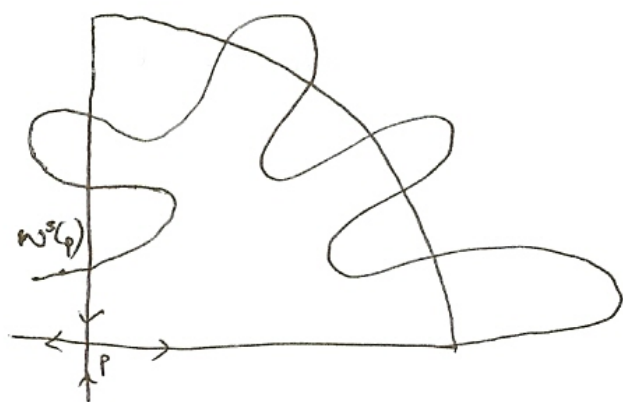
Thm: $M-S$ vector fields form an open set in the space of C^1 -vector fields on M . Each $M-S$ vector field is structurally stable.

Warning: $M-S$ systems are not dense and there are many other structurally stable diff and flows.

ONLY on S^1 $M-S \iff$ structurally stable

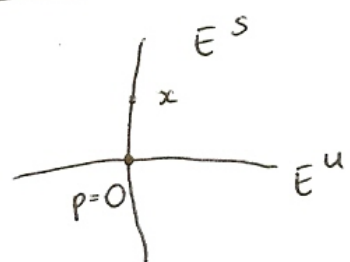
Last time we almost discovered that $M-S$ diff on S^2 cannot be dense, since we discovered homoclinic points

Thm: If $f: M \rightarrow M$ is a C^1 -diff, p -hyperbolic fixed point and there is a homoclinic point x (i.e. $W^s(p), W^u(p)$ intersect transversally at p). Then there exists a hyperbolic invariant set Λ such that the dynamics of $f^N|_\Lambda$ is conjugate to $H|_{\Omega(H)}$



H - horseshoe

Proof: (outline)



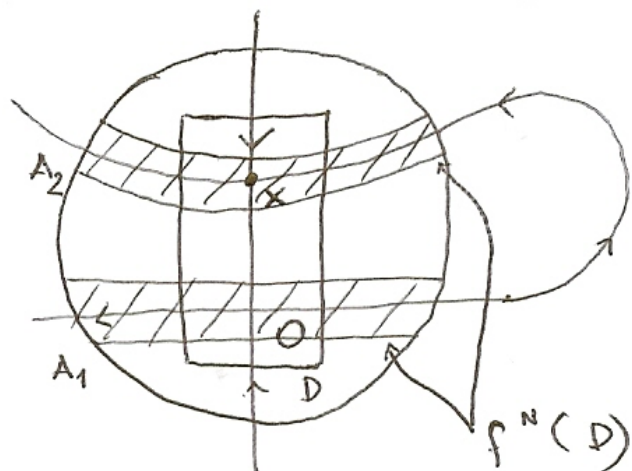
$$\begin{pmatrix} x & y \\ \uparrow & \uparrow \\ E^u & E^s \end{pmatrix},$$

$$W_E^u(p) = (x, \varphi^u(x))$$

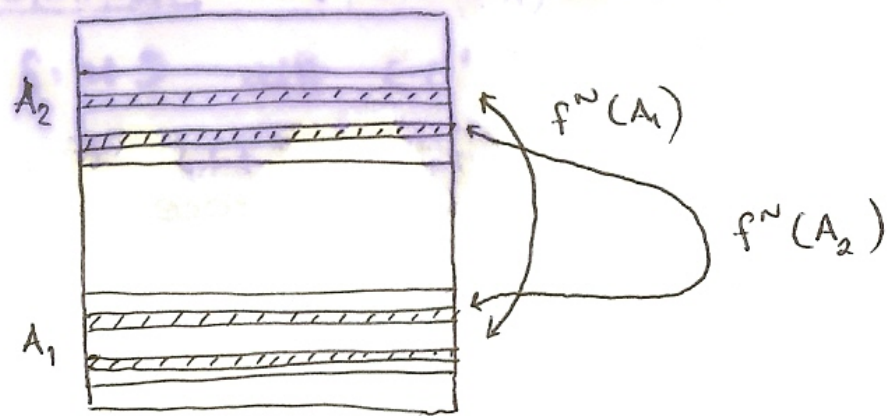
$$W_E^s(p) = (\varphi^s(y), y)$$

change of coordinates

$$\varphi(x, y) = (x - \varphi^s(y), y - \varphi^u(x))$$



we claim, that for some N the intersection $f^N(D) \cap D$ has two components A_1, A_2 .



The precise calculation is based on so called λ -lemma (or Induction lemma)

p -hyperbolic fixed point, $W_\varepsilon^u(p)$ - a "piece" of stable manifold or $f^M(W_\varepsilon^u(p))$ for some M .

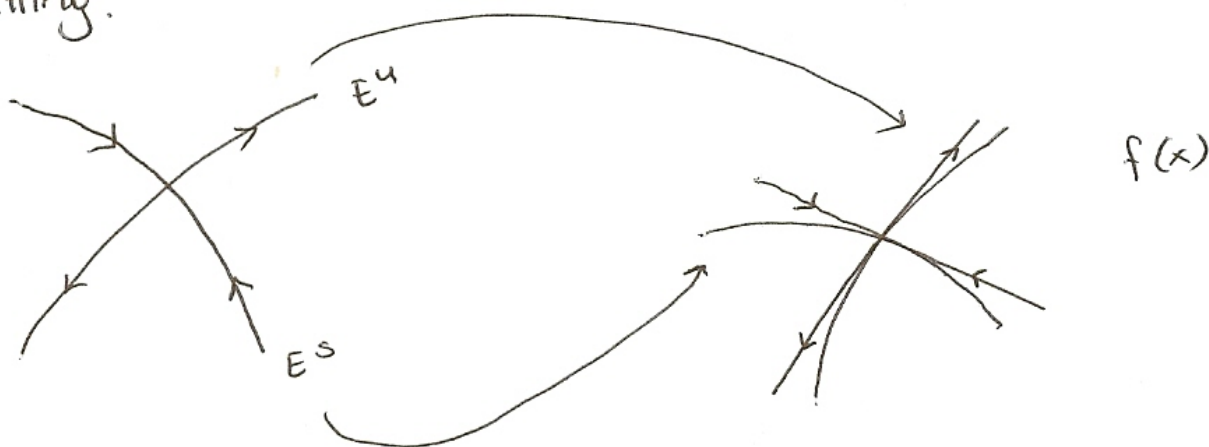
If D^u is a small disc (n -dimensional), transversal to $W^s(p)$ at x then for all $N \gg 0$.

$f^N(D^u)$ contains an open subset which is ε - C^1 -close to $W_\varepsilon^u(p)$

Recall: $f: M \rightarrow M$ diff, M -compact, we may assume that $f: U \rightarrow M$ for some nbd of Λ

Λ -hyperbolic set - compact, f -invariant

Recall, that at each point $x \in \Lambda$ there is an invariant splitting.



Theorem: (on existence of $W_\varepsilon^s(x)$, $W_\varepsilon^u(x)$ for hyperbolic sets)
If Λ is h.s. then there exists $\varepsilon, \tilde{\lambda}$ s.t. for every $x \in \Lambda$:

$$W_\varepsilon^s(x) = \{ y: d(f^n(x), f^n(y)) < \varepsilon \quad \forall n \geq 0 \} = \\ = \{ y: d(f^n(x), f^n(y)) < C \tilde{\lambda}^{-n} \text{ for all } n \geq 0 \}$$

is a smooth manifold, tangent to $E^s(x)$ at x .

Moreover $f(W_\varepsilon^s(x)) \subset W_\varepsilon^s(f(x))$

Measure preserving transformation:

$(X, \mathcal{M}, \mu)$ X - a set, $\mathcal{M}$ - a field of subsets of X , μ - measure, μ - finite
(σ -field)

$T: X \rightarrow X$, we always assume that T is μ -measurable, i.e.
 $\forall A \in \mathcal{M} \quad T^{-1}(A) \in \mathcal{M}$.

Def: we say that T preserves the measure μ (or μ is T -invariant) if $\forall A \in \mathcal{M} \quad \mu(T^{-1}(A)) = \mu(A)$ (T -endomorphism of X)

Remark: If T is invertible, then μ is T -invariant $\Leftrightarrow \mu(T(A)) = \mu(A)$ (T -automorphism of X)

Fact: T preserves μ iff for every function $f: X \rightarrow \mathbb{R}$, $f \in L_1(\mu)$
 $\int f \circ T d\mu = \int f d\mu \quad (*)$

Proof: If $f = \chi_A$ for $A \in \mathcal{M}$, then

$$\int f \circ T d\mu = \int \chi_A(T(x)) d\mu(x) = \int \chi_{T^{-1}(A)}(x) d\mu(x) = \mu(T^{-1}(A))$$

$$\int f d\mu = \int \chi_A d\mu = \mu(A)$$

This gives the proof of " $\Leftarrow$ "

$\Rightarrow$ we have $(*)$ for $f = \chi_A$ $A \in \mathcal{M}$

Then the standard proof from integration theory

indication functions $\Rightarrow$ simple function $\Rightarrow$ measurable - positive functions
 $\Rightarrow L^1$ functions

Remark: $U(f) = f \circ T$ $\leftarrow$ operator on $L^1(\mu)$
 $L^2(\mu)$
(Koopman operator)

(spectral theory)

Examples of measure preserving transformations:

1) Rotation of the circle - it preserves Lebesgue measure, T -automorphism

2) Rotation of the torus $\mathbb{T}^n = \mathbb{R}^n / \mathbb{Z}^n$

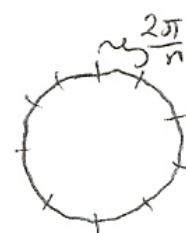
$$(x_1, \dots, x_n) \mapsto (x_1 + \alpha_1, \dots, x_n + \alpha_n) \bmod 1 \quad \alpha_1, \dots, \alpha_n \in \mathbb{R}$$

(generalization: the Haar measure on a locally compact group)

(3) $X = S^1 \subset \mathbb{C}$

$$T(z) = z^n, \quad n \in \mathbb{Z} \setminus \{0\}$$

$$T(x) = nx \bmod 1, \quad x \in [0, 1]$$



each arch goes to the full circle

Lebesgue measure preserved

4) Gauß transformation

$$T: [0, 1] \rightarrow [0, 1] \quad T(x) = \frac{1}{x} - \left[\frac{1}{x} \right] = \left\{ \frac{1}{x} \right\}$$

- fraction part of $\frac{1}{x}$

It is well defined and values are in the set $[0, 1]$

8) Liouville theorem: If M - smooth manifold, V - smooth vector field on M , $\{\varphi_t\}$ flow defined by M .

If $\text{div } V = 0$ then φ_t preserves Lebesgue measure on M .

Poincare recurrence theorem (tw Poincarego o powracaniu) (1899)

$(X, \mathcal{M}, \mu)$ - measurable space, $T: X \rightarrow X$, μ - finite

Def: A point $x \in X$ is recurrent w.r.t. a set $A \in \mathcal{M}$ if $\exists n > 0$ s.t. $T^n(x) \in A$

Theorem (PRT) If T preserves μ , then for every $A \in \mathcal{M}$, μ - almost every point of A is recurrent with respect to A .

Corollary: μ - a.e. point of A returns to A infinitely many times

Proof: $B = \{x \in A \mid \forall n > 0 \quad T^n(x) \in A\}$

Let $B_n = T^{-n}(B)$

Then B_n are pairwise disjoint. Because if $x \in B_k \cap B_l$, $k > l$

$x \in T^{-k}(B) \cap T^{-l}(B)$

$T^k(x) = T^{k-l}(T^l(x))$ it's contradiction

$\begin{matrix} \uparrow & & \uparrow \\ B & & B \\ \cap & & \cap \\ A & & A \end{matrix}$

Moreover, since μ is T invariant $\forall n \quad \mu(B_n) = \mu(B)$.

$\mu\left(\bigcup_{n=1}^{\infty} B_n\right) = \sum_{n=1}^{\infty} \mu(B) \leq \mu(X) < \infty$

$\mu(B) = 0$

□

Def: $A \in \mathcal{M}$, $\mu(A) > 0$

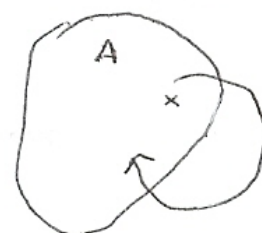
$x \in A$, $n_A(x) = \inf \{n > 0 : T^n(x) \in A\}$

by PRT, n_A is well-defined almost everywhere on A

n_A - first return time to A

$T_A: A \rightarrow A$ the first return map to A (induced map) it's well defined almost everywhere on A

$T_A(x) = T^{n_A(x)}(x)$



T_A preserves μ

Kakutani diagram (tower) ~ 1940

$A_k = \{x \in A : n_A(x) = k\}$ $k = 1, 2, \dots$

$A = \bigcup_{k=1}^{\infty} A_k$ (up to zero-measure set)

8) Liouville theorem: If M - smooth manifold, V - smooth vector field on M , $\{\varphi_t\}$ flow defined by M .

If $\text{div } V = 0$ then φ_t preserves Lebesgue measure on M .

Poincaré recurrence theorem (tw Poincarego o powracania) (1899)

$(X, \mathcal{M}, \mu)$ - measurable space, $T: X \rightarrow X$, μ - finite

Def: A point $x \in X$ is recurrent w.r.t. a set $A \in \mathcal{M}$ if $\exists n > 0$ s.t. $T^n(x) \in A$

Theorem (PRT) If T preserves μ , then for every $A \in \mathcal{M}$, μ - almost every point of A is recurrent with respect to A .

Corollary: μ - a.e. point of A returns to A infinitely many times

Proof: $B = \{x \in A \mid \forall n > 0, T^n(x) \notin A\}$

Let $B_n = T^{-n}(B)$

Then B_n are pairwise disjoint. Because if $x \in B_k \cap B_l$, $k > l$

$x \in T^{-k}(B) \cap T^{-l}(B)$

$T^k(x) = T^{k-l}(T^l(x))$ it's contradiction

$\begin{matrix} \cap \\ B \\ \cap \\ A \end{matrix}$ $\begin{matrix} \cap \\ B \end{matrix}$

Moreover, since μ is T invariant $\forall n, \mu(B_n) = \mu(B)$.

$\mu(\bigcup_{n=1}^{\infty} B_n) = \sum_{n=1}^{\infty} \mu(B)$ so $\mu(B) = 0$

$\mu(x) < \infty$

■

Def: $A \in \mathcal{M}$, $\mu(A) > 0$

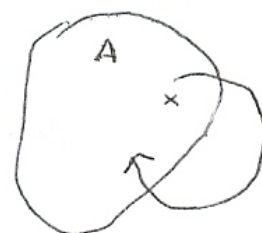
$x \in A$, $n_A(x) = \inf \{n > 0 : T^n(x) \in A\}$

by PRT, n_A is well-defined almost everywhere on A

n_A - first return time to A

$T_A: A \rightarrow A$ the first return map to A (induced map) $\leftarrow$ it's well defined almost everywhere on A

$T_A(x) = T^{n_A(x)}(x)$

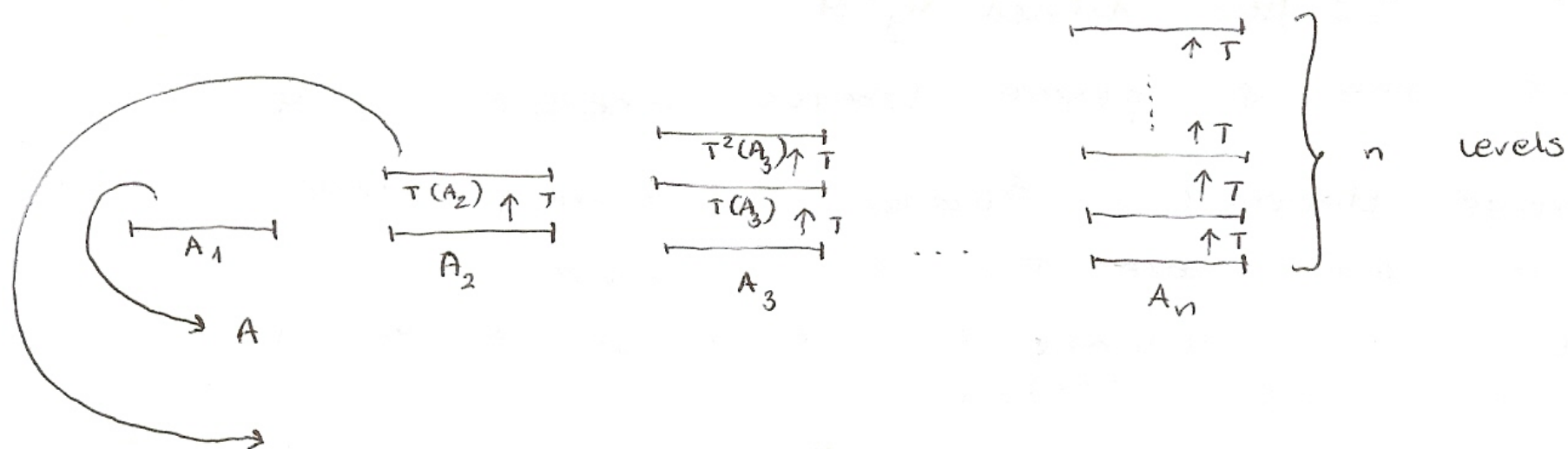


T_A preserves μ

Kakutani diagram (tower) ~ 1940

$A_k = \{x \in A : n_A(x) = k\}$ $k = 1, 2, \dots$

$A = \bigcup_{k=1}^{\infty} A_k$ (up to zero-measure set)



$$T(A_2) = (TA \setminus A)_2$$

$$T(A_3) = (TA \setminus A)_3$$

$$T^2(A_3) = (T^2A \setminus A)$$

Dynamics on the tower is given by arrows. Tower is forward invariant ($T(I) \subset I$ by construction).

Note that $T^{-1}(J) \setminus J$ has measure 0. So we can neglect it:
 $\uparrow$
 tower

(Points from $T^{-1}(J) \setminus J$ never return to $T^{-1}(J) \setminus J$, use PRT)

Corollary: The first return map $-T_A$ preserves measure $\mu|_A$

Proof: Looking at the tower

Ergodic theorems: $(X, \mathcal{F}, \mu)$ - measurable space, μ -finite, $T: X \rightarrow X$ preserves μ .

1. Maximal ergodic theorem (Wiener - Yosida - Kakutani 1938)

$$\forall f \in L^1(\mu) \quad f: X \rightarrow \mathbb{R} \quad \text{if} \quad S_n(x) = f(x) + f(T(x)) + f(T^2(x)) + \dots + f(T^{n-1}(x))$$

$$\text{then} \quad \int f d\mu \geq 0$$

$$\{x \in X: \sup_n S_n(x) > 0\}$$

Proof: $A = \{x: \sup_n S_n(x) > 0\}$, $S_n(x) = \max(S_1(x), \dots, S_n(x))$

$$A_n = \{x: S_n(x) > 0\}, \quad S_n^*(x) = \max(S_n(x), 0)$$

By definition $S_{n+1}(x) = f(x) + S_n^*(Tx)$

(if $S_n^*(Tx) = S_n(Tx)$ then $R = f(x) + S_n(Tx) = f(x) + f(Tx) + \dots + f(T^n(x)) = 1$
 $1 \leq k \leq n$)

if $S_n^*(Tx) = 0$ then $L = R = f(x)$

$$\int_A f = \int_A (S_{n+1} - S_n^* \circ T) \geq \int_A (S_n - S_n^* \circ T)$$

$$\int_{A_n} f = \int_{A_n} (S_{n+1} - S_n^* \circ T) \geq \int_{A_n} (S_n - S_n^* \circ T) = \int_{A_n} (S_n^* - S_n^* \circ T) = 0$$

$S_{n+1} \geq S_n$ $S_n^* = S_n$ on A_n

$$= \int_X S_n^* - \int_{A_n} S_n^* \circ T \geq \int_X S_n^* - \underbrace{\int_X S_n^* \circ T}_{\text{It's non-negative}} = 0$$

$$\text{so } \int_A f = \int_{\bigcup_{n=1}^{\infty} A_n} f \geq 0 \quad \square$$

Theorem (Birkhoff ergodic theorem) 1931

$\forall f \in L^1$

$$a) \quad \frac{1}{n} f(x) + f(T(x)) + \dots + f(T^{n-1}(x)) \xrightarrow{n \rightarrow \infty} \bar{f}(x) \quad \mu \text{ almost everywhere and in } L^1$$

$$b) \quad \bar{f} \text{ T-invariant, } \bar{f} \in L^1, \|\bar{f}\|_1 \leq \|f\|_1$$

$$c) \quad \int_A \bar{f} d\mu = \int_A f d\mu \quad \forall \text{ T-invariant set } A \in \mathcal{T} \quad (A = T^{-1}(A))$$

$$\bar{f} = \mathbb{E}(f | \mathcal{G}) \quad \mathcal{G} = \sigma\text{-field of T-invariant set.}$$

Proof: a) $S_n(x) = f(x) + \dots + f(T^{n-1}x)$

Suppose $\frac{S_n(x)}{n}$ does not converge on a set of positive measure.

$$\text{Then } \underline{\lim} \frac{S_n(x)}{n} < b < a < \overline{\lim} \frac{S_n(x)}{n} \text{ for } a, b \in \mathbb{R} \quad \forall x \in A, \mu(A) > 0$$

Since A is compl. invariant we can assume $A = X$.
we can rescale f taking $\alpha f + \beta$ instead of f
($\alpha, \beta \in \mathbb{R}$), we can assume that $a = 1, b = -1$

$$\text{so } \overline{\lim} \frac{S_n(x)}{n} > 1 \quad \forall x \in X \quad \text{Then } \sup_n S_n(x) > 0$$

$$\underline{\lim} \frac{S_n(x)}{n} < -1 \quad \text{by MET } \int_X f \geq 0$$

Take $-f$ instead of f. Then by MET $\int_X f \leq 0$ so $\int_X f = 0$.

Take $f + \frac{1}{2}$ instead of f then for suitable $S_n(x)$ we have

$$\overline{\lim} \frac{S_n(x)}{n} > \frac{3}{2} \quad \underline{\lim} \frac{S_n(x)}{n} < -\frac{1}{2}$$

Doing the same as previously we get

$$\int_X (f + \frac{1}{2}) = 0$$

$\Downarrow$

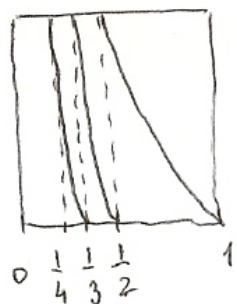
$$\int_X d\mu = 0 \quad \square$$

Examples: The Gauß map

$$T(x) = \frac{1}{x} - \left[\frac{1}{x} \right] = \left\{ \frac{1}{x} \right\} \leftarrow \text{fraction}$$

$$x \in (0, 1]$$

$$T: [0, 1] \rightarrow [0, 1]$$



relation to continued fractions (ciągły Eulera)

$$0 < x < 1$$

$$x = \frac{1}{a_1 + \frac{1}{a_2 + \dots}} = [a_1, a_2, \dots] \quad a_1, \dots \in \mathbb{N}$$

$$T([a_1, a_2, \dots]) = [a_2, a_3, \dots]$$

Fact: If μ is the absolute continuous with density $\frac{1}{1+x}$ (i.e. $\mu(A) = \int_A \frac{dx}{1+x}$) then μ is T -invariant

It's enough to show $\mu(A) = \mu(T^{-1}(A))$ for A Borel, so

||

$A = [a, b]$, so

||

$A = [0, a]$.

So it is enough to check $\int_0^a \frac{dx}{1+x} = \mu([0, a]) \stackrel{?}{=} \mu(T^{-1}([0, a]))$

$$\ln(a+1) = \sum_{n=1}^{\infty} \int_{I_n} \frac{dx}{1+x} \quad (I_n = [\frac{1}{n+a}, \frac{1}{n}])$$

$$= \sum_{n=1}^{\infty} \ln \left(\frac{1 + \frac{1}{n}}{1 + \frac{1}{n+a}} \right) =$$

$$= \prod_{n=1}^{\infty} \ln \left(\frac{1 + \frac{1}{n}}{1 + \frac{1}{n+a}} \right)$$

$$= \lim_{N \rightarrow \infty} \ln \left(\prod_{k=1}^N \frac{1 + \frac{1}{k}}{1 + \frac{1}{k+a}} \right)$$

$$= \lim_{N \rightarrow \infty} \ln \left(\prod_{k=1}^N \frac{k+1}{k+1+a} \cdot \frac{k+a}{k} \right)$$

$$= \lim_{N \rightarrow \infty} \ln \left(\frac{N+1}{N+1+a} \cdot 1+a \right)$$

$\ln$ is continuous so we may pass the limit under the function

$$= \ln(1+a)$$

Q

Homework

1. Algebraic total automorphism

Let A integer matrix $n \times n$

$$T(x) = Ax \quad T: \mathbb{T}^n \rightarrow \mathbb{T}^n \quad \det A = \pm 1$$

$$\mathbb{T}^n = \mathbb{R}^n / \mathbb{Z}^n$$

check that T is 1-1 on $\mathbb{T}^n$ and T preserves Leb. measure

$$2. \text{ Let } B(z) = \prod_{k=1}^n e^{it_k \frac{z - a_k}{1 - \overline{a_k} z}} \quad z \in \mathbb{D}$$

$$B(S^1) = S^1$$

$$a_k \in \mathbb{D}, \quad |a_k| < 1, \quad t_k \in \mathbb{R}$$

Check that B preserves Lebesgue measure if there $\exists_k$ s.t. $a_k = 0$

20.05.2011

$$(X, \mathcal{F}, \mu, T)$$

$$\mu(T^{-1}A) = \mu(A)$$

$$f \in L^1(\mu)$$

$$\frac{f + f \circ T + \dots + f \circ T^{n-1}}{n} \xrightarrow[n]{\text{a.e. } L^1} E(f|g) = \bar{f}$$

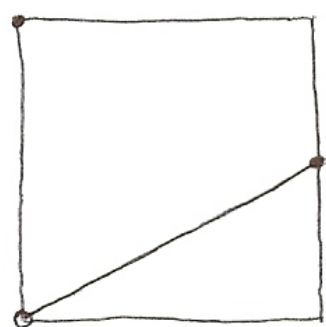
Def: The map T is ergodic with respect to μ iff g is trivial
(equivalently: (via ergodic thm) T is ergodic iff $\forall f \in L^1$

$$\frac{f + \dots + f \circ T^{n-1}}{n} \xrightarrow[n]{\text{a.e. } L^1} \int f d\mu$$

$$E(E(f|g)) = E(f) = \int f d\mu$$

Question: $(X, \mathcal{F}, T)$. Does there exist any invariant measure?

Answer: Example Consider the map $T: [0, 1] \rightarrow [0, 1]$ $T(x) = \begin{cases} \frac{1}{2}x & x \neq 0 \\ 1 & x = 0 \end{cases}$



Assume that there is an invariant measure μ . Then

$$\dots = \mu([0, \frac{1}{4}]) = \mu([0, \frac{1}{2}]) = \mu(T^{-1}([0, \frac{1}{2}])) = \mu([0, 1])$$

$$\Rightarrow \mu([0, 1]) = 0 \quad \Rightarrow \mu(\{0\}) = 1$$

but it is not invariant as $0 \rightarrow 1$

Theorem (Krylov, Bogoliubov): If X is metric compact space and $T: X \rightarrow X$ is continuous then there is a Borel, regular T -invariant measure μ .

Proof: Take an arbitrary measure e.g. δ_x

Consider a sequence of measures

$$\mu_n = \frac{\delta_x + \delta_{Tx} + \dots + \delta_{T^{n-1}x}}{n}$$

then there exists a measure subsequence $\mu_{n_i} \xrightarrow[\ast]{\text{weakly}} \mu$ (some

Borel, regular measure)

$$T_{\ast} \mu \stackrel{\text{def}}{=} \mu(f \circ T)$$

$$\mu_n = \frac{\delta_x + T_{\ast} \delta_x + \dots + T_{\ast}^{n-1} \delta_x}{n}$$

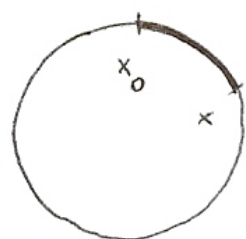
$$\text{Then } T_{\ast}(\mu_{n_i}) = \frac{T_{\ast}(\delta_x + T_{\ast} \delta_x + \dots + T_{\ast}^{n_i-1} \delta_x)}{n_i} = \frac{T_{\ast} \delta_x + \dots + T_{\ast}^{n_i} \delta_x}{n_i} =$$

$$T_{\ast}(\mu) \xleftarrow{W^{\ast}} = \frac{\delta_x + \dots + T_{\ast}^{n_i-1} \delta_x}{n_i} + \frac{T_{\ast}^{n_i} \delta_x - \delta_x}{n_i} \rightarrow \mu \quad \rightarrow 0$$

$$T_* \mu_{n_i}(f) = \mu_{n_i}(f \circ T) \rightarrow \mu(f \circ T) = T_* \mu$$

$\mu: T_* \mu = \mu$ $\mu(f \circ T) = \mu(f)$ for every continuous function

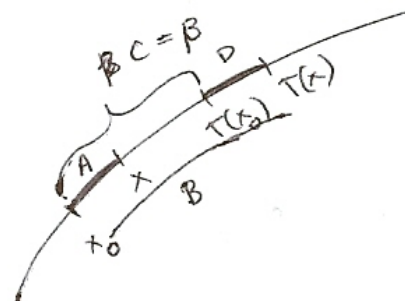
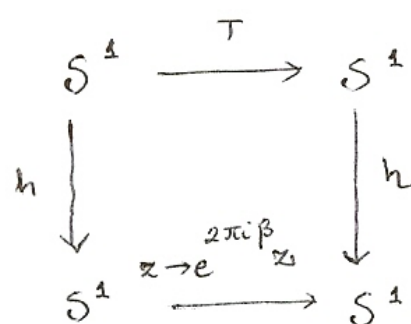
Example: Let $T: S^1 \rightarrow S^1$ be homeomorphism of S^1 of degree 1, $\alpha = \int (T)$ rational. Then (by K-B thm) there exists an invariant measure μ on S^1 , μ is non-atomic



$[x_0, x]$

Define $h: S^1 \rightarrow S^1$

$$h(x) = e^{2\pi i \mu [x_0, x]}$$

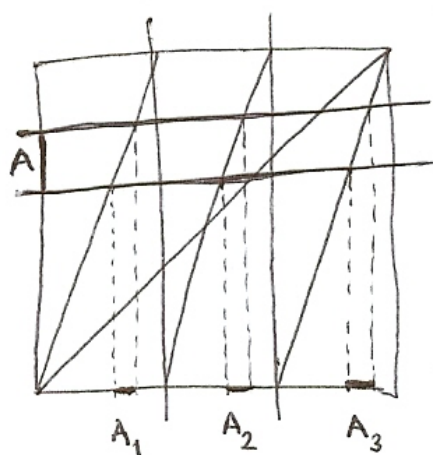


$$h(T(x)) = e^{2\pi i \mu [x_0, T(x)]} = e^{2\pi i (C+D)} = e^{2\pi i C} \cdot e^{2\pi i D} = e^{2\pi i \beta} h(x)$$

$$\alpha = \beta$$

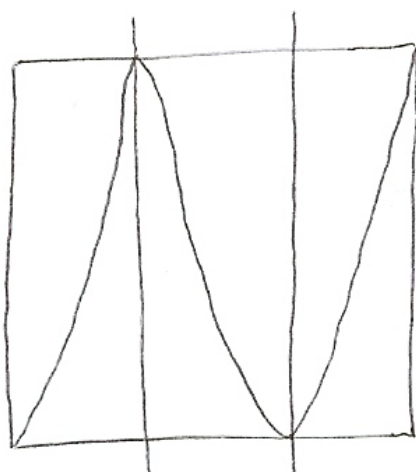
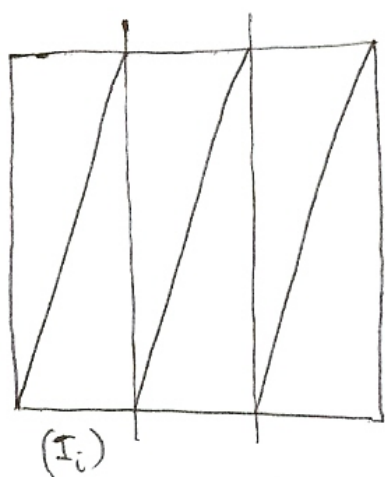
invariant measures a.c. with respect to Lebesgue measure

Example



Lebesgue measure is invariant

$$|A| = |A_1| + |A_2| + |A_3|$$



$$[0, 1] = \cup I_i = \cup [a_i, a_{i+1}] \quad (\text{the last one } [a_j, 1])$$

$f|_{I_i}$ is C^2 on some neighbourhood of I_i

$$f|_{I_i} \rightarrow [0, 1]$$

$f|_{I_i}$ expanding i.e. $|f'| > \lambda > 1$

Assumptions implies that $\log |f'|$ is Lipschitz continuous with some constant L .

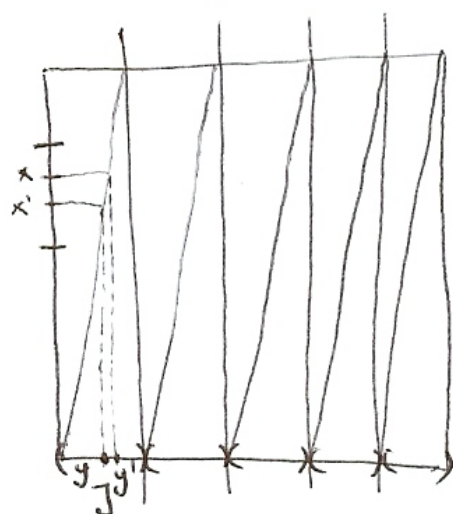
Theorem: This map has exactly one ergodic invariant measure μ a.c. with respect to measure L and

$$C^{-1} < \frac{d\mu}{dL} < C \quad \text{for some } C > 0$$

Proposition: Let $\nu_n = T_*^{-n} L$ ($\nu_n(A) = L(T^{-n}A)$). Then ν_n is a.c. with respect to L with density

$$g_n(x) = \sum_{y \in T^{-n}(x)} \frac{1}{|(T^n)'(y)|}$$

We shall check that $C^{-1} \leq g_n(x) \leq C$ for all n and some C independent of n .



T^n monotone

$$J \xrightarrow{T} T(J) \xrightarrow{T} T^2(J) \rightarrow \dots \rightarrow T^{n-1}(J) \xrightarrow{T} [0, 1]$$

$$\begin{array}{c} \begin{array}{c} y \\ y' \end{array} \xrightarrow{T} \begin{array}{c} T y \\ T y' \end{array} \xrightarrow{T} \begin{array}{c} T^2 y \\ T^2 y' \end{array} \xrightarrow{T} \dots \xrightarrow{T} \begin{array}{c} T^{n-1} y \\ T^{n-1} y' \end{array} \xrightarrow{T} \begin{array}{c} x \\ x' \end{array} \end{array}$$

$k \leq n: |T^k(J)| \leq \frac{1}{\lambda^{n-k}}$

$$\frac{g_n(x)}{g_n(x')} = \frac{\sum_y \frac{1}{|(T^n)'(y)|}}{\sum_{y'} \frac{1}{|(T^n)'(y')|}}$$

Let us fix a preimage $y \in T^{-n}(x)$ and $y' \in T^{-n}(x')$ paired with y in the way just described.

$$\left| \log \frac{|(T^n)'(y')|}{|(T^n)'(y)|} \right| = \left| \sum_{k=0}^{n-1} \log |T'(T^k(y'))| - \log |T'(T^k(y))| \right| \leq L \sum_{k=0}^{n-1} \frac{1}{\lambda^{n-k}} \leq C$$

We have checked

$$\frac{g_n(x)}{g_n(x')} < C \quad \text{by symmetry} \quad C^{-1} < \frac{g_n(x)}{g_n(x')}$$

Now: recall that $\int g_n = 1 \Rightarrow \exists x' \text{ s.t. } g_n(x') \leq 1 \Rightarrow g_n(x) \leq C$

$$\nu_n = g_n \cdot L$$

$$\mu_n = \frac{\nu_0 + \nu_1 + \dots + \nu_{n-1}}{n}$$

$$\mu_{n_i} = h_{n_i} \cdot L$$

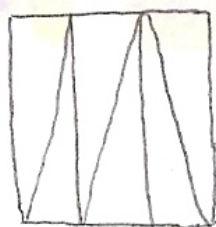
$$C^{-1} \leq h_n \leq C$$

$\downarrow$

$$\mu \quad \forall A \quad \mu(\partial A) = 0 \quad \mu_{n_i}(A) \rightarrow \mu(A)$$

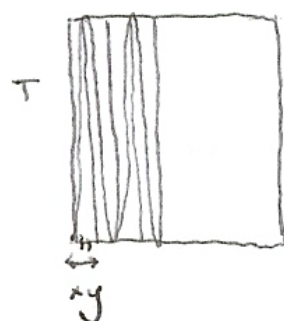
27.05.2011

Ergodicity of invariant measure:

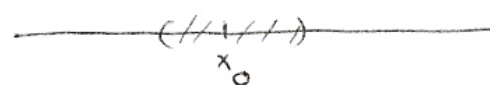


$$\log \left| \frac{(f^n)'(x)}{(f^n)'(y)} \right| < C$$

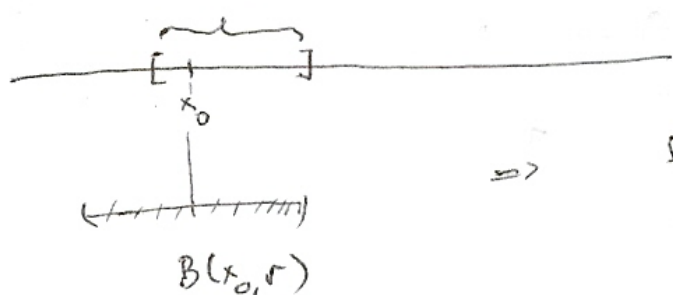
Assume $A \subset I$ is a Borel invariant set
 $T^{-1}(A) = A$
 $0 < \mu(A) < 1$
 $\Downarrow$
 $0 < \text{Leb}(A) < 1$



Take a density point of $A(x_0)$



$I_n(x_0)$ - piece of monotonicity of f^n , containing x_0



$\Rightarrow$ for large n $\frac{\text{Leb}(I_n(x_0) \cap A)}{\text{Leb}(I_n(x_0))} \rightarrow 1$

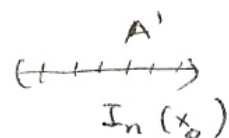


$$\frac{\text{Leb}(B(x_0, r) \cap A)}{\text{Leb}(B(x_0, r))} \xrightarrow{r \rightarrow 0} 1$$

$$\text{Leb}(A \cap I_n(x_0)) = \text{Leb}(T^{-n}A \cap I_n(x_0)) \geq \inf_{I_n(x_0)} \frac{1}{|(T^n)'|} \cdot \text{Leb}(A')$$

$$\text{Leb}(I_n(x_0)) \leq \sup_{I_n(x_0)} \frac{1}{|(T^n)'|}$$

$$\frac{\text{Leb}(A' \cap I_n(x_0))}{\text{Leb}(I_n(x_0))} \geq \inf_{I_n(x_0)} \left| \frac{(T^n)'(x)}{(T^n)'(y)} \right|$$



$$> c > 0$$

Hyperbolic sets - Ergodicity

Example: $T: \mathbb{T}^2 \rightarrow \mathbb{T}^2$ hyperbolic isomorphism of $\mathbb{T}^2$

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

Proposition: The Lebesgue measure $\text{Leb}|_{\mathbb{T}^2}$ (invariant for T) is ergodic.

(This argument is very general!)

Proof: we want to show that for every $h \in L^1(\text{Leb})$

$$(*) \frac{1}{n} \sum_{i=0}^{n-1} h \circ T^i \rightarrow \int h d\text{Leb}$$

$$(*) \frac{1}{n} \sum_{i=0}^{n-1} h \circ T^i \rightarrow \int h d\text{Leb}$$

① we prove (*) for $h=g$ - continuous.

we know from Birkhoff ergodicity theorem that

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^i = \mathbb{E}(g | G_+)$$

$$G_+ = \{A: \text{Leb}(T^{-1}(A) \triangle A) = 0\}$$

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^{-i} = \mathbb{E}(g | G_-) \quad G_- = \{A : \text{Leb}(T(A) \div A) = 0\}$$

1 from (x x)
Sgalleb

$$G_+ = G_-$$

Theorem:

for a.e. $x_0 \in \mathbb{T}^2$

$$\{x_0: \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^{-i}\}$$

$$G \cong \text{Leb}(G) = 1$$

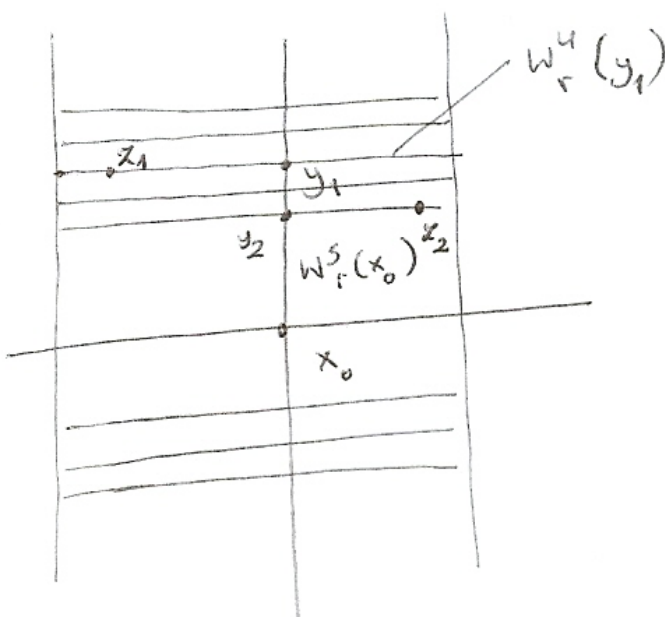


A vertical line with a point labeled x_0 and a label $W_r^s(x_0)$ above it.

There exist a set F of full measure in $\mathbb{T}^2$ s.t. for every $x_0 \in F$:

$$\text{Leb}_1(W_r^S(x_0) \cap G) = \text{full measure in } W_r^S(x_0)$$

$$y \in W_r^s(x_0) \cap G$$



We have checked that

We have checked

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^{-i}(z_1) = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g \circ T^{-i}(z_2) \quad (* *)$$

It remains to prove the statement for an arbitrary $h \in L^4$

$$C(T^2) \ni g_n \xrightarrow{L_1} h \quad \|g_n - h\|_{L^1} \rightarrow 0$$

$$h_T = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n h \circ T^i = \int |g - h| d\mu_b < \varepsilon \quad g \in C(T^2)$$

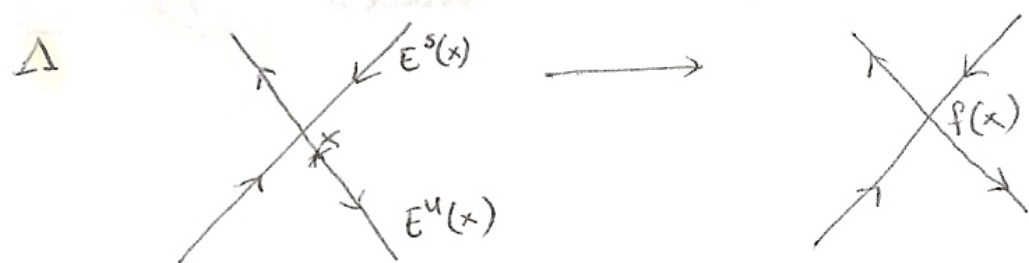
$$= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n g(t_i) \tau_i + \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n (h - g(t_i)) \tau_i$$

f is measurable, preserves measure

$$(h_T - Sg) = \lim \frac{1}{n} \sum_{i=0}^{n-1} (h - g) \circ T^i = \|h - g\|_{L^1} < \varepsilon$$

Thus h_+ differs (in L^1) from a constant $\int g$ by less than ε .

Hyperbolic sets:



Proposition: Let Λ be a hyperbolic set. Then $E^u(x)$, $E^s(x)$ depend continuously on x .

x_n $v_1^n \dots v_s^n$ - orthonormal basis in $E^s(x_n)$
 it may be a sub-sequence $\downarrow$ $v_1^0 \dots v_s^0$
 We claim that $v_1^0, \dots, v_s^0 \in E_x^s$.

$$v_1^n \in E^s(x_n) \quad \lambda > 1$$

$$\|D_{x_n}^k f(v_1^n)\| < \lambda^{-k} \|v_1^n\|$$

$\downarrow n \rightarrow \infty$

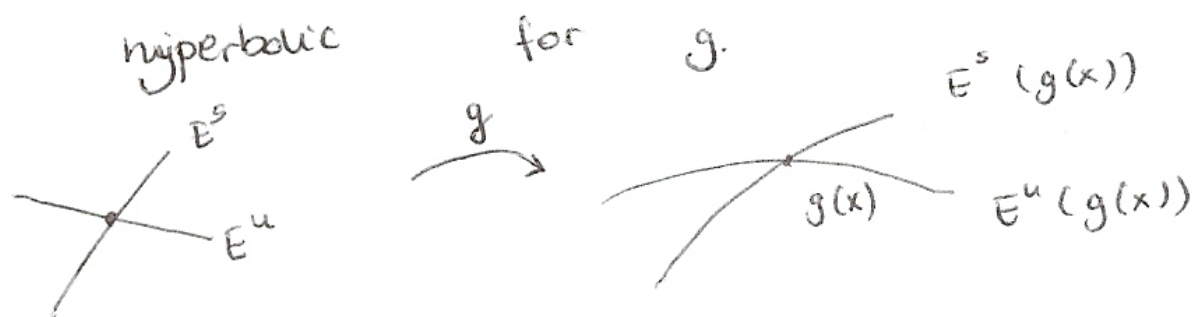
$$\|D_x^k f(v_1^0)\| < \lambda^{-k} \|v_1^0\|$$

3.06.2011

stability of hyperbolic sets:

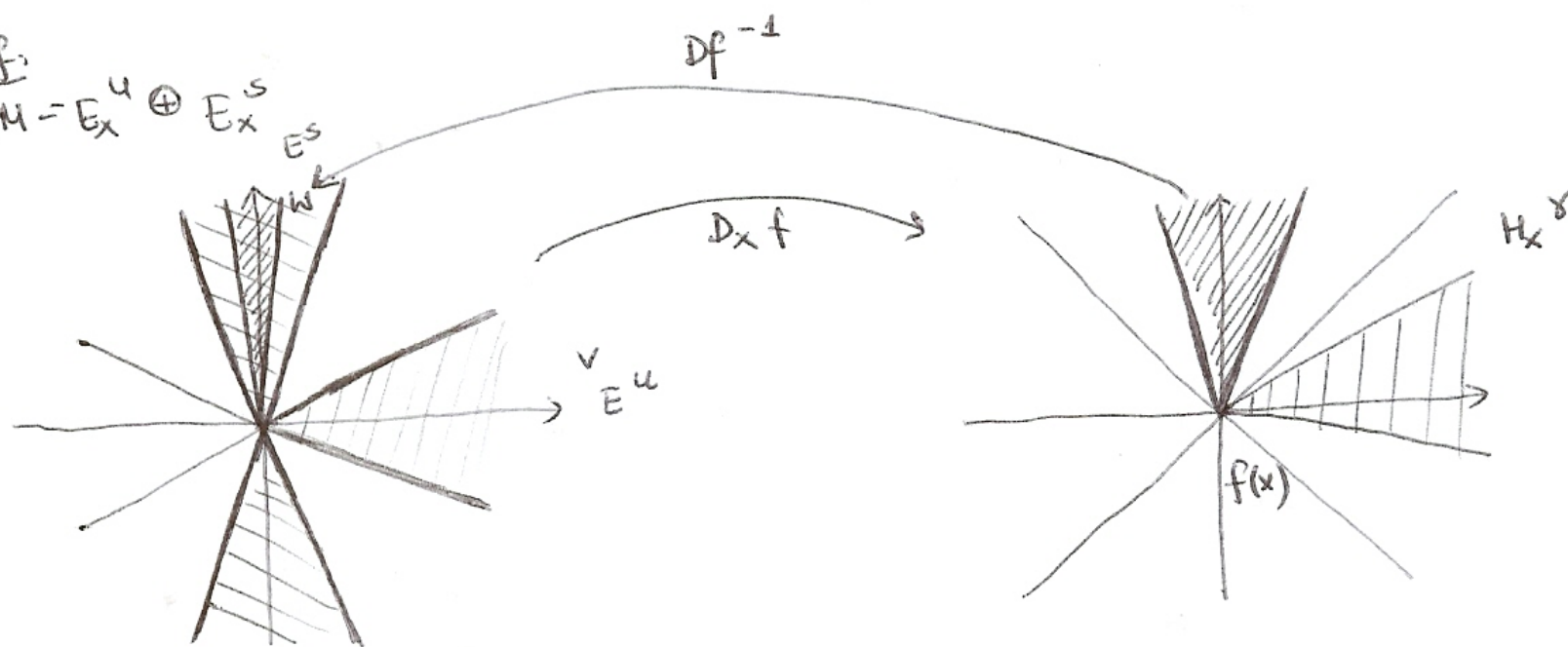
Proposition: Let Λ be a hyperbolic set for $f: M \rightarrow M$ and let $g: M \rightarrow M$ be sufficiently close to f (in C^1 metric). Then there exists a neighbourhood $V > \Lambda$ in M

such that the set $\Lambda_g^V = \{x: \forall n \quad g^n(x) \in V\}$ is hyperbolic for g . ~~jest zbiorem hiperbolicznym~~



Proof:

$$T_x M = E_x^u \oplus E_x^s$$



$$H_x^\delta = \left\{ \underbrace{v}_{\in E^u} + \underbrace{w}_{\in E^s} : \|w\| \leq \gamma \|v\| \right\}$$

$$V_x^\gamma = \{ (v+w) : \|v\| \leq \gamma \|w\| \}$$

$$\|D_x f^n(w)\| \leq C \|w\| \lambda^{-n}$$

$$\|D_x f^n(v)\| \geq \|v\| \lambda^n$$

$$(*) \quad D_x f(H_x^\gamma) \subset H_{f(x)}^\gamma \lambda^{-2}$$

we have a splitting for Λ . we already know that E_x^s ,

E_x^u depend continuously on $x \in \Lambda$. we extend the splitting

E_x^s, E_x^u continuously to some neighbourhood of Λ .

we check that $(*)$ holds not only in Λ but

also in some neighbourhood of Λ .

Lemma: Let $L_m: \mathbb{R}^u \oplus \mathbb{R}^s \rightarrow \mathbb{R}^u \oplus \mathbb{R}^s$ be a sequence of linear maps

$$(1) \quad L_m(H^\gamma) \subset \text{Int } H^\gamma \quad \lambda > 1$$

$$(2) \quad L_m^{-1}(V^\gamma) \subset \text{Int } V^\gamma$$

$$(3) \quad \|L_m(u)\| \geq \lambda \|u\| \quad \text{for } u \in H^\gamma$$

$$(4) \quad \|L_m(u)\| \leq \lambda^{-1} \|u\| \quad \text{for } u \in V^\gamma$$

Then $E_m^u = \bigcap_{i=0}^{\infty} L_{m-1} \circ L_{m-2} \circ \dots \circ L_{m-i} H^\gamma$

is a family of invariant subspaces: $L_m: E_m^u \rightarrow E_{m+1}^u$

Invariant splitting

$$E_m^u \oplus E_m^s$$

$$E_m^s = \bigcap_{i=0}^{\infty} L_m^{-1} \circ L_{m+1}^{-1} \circ \dots \circ L_{m+i}^{-1} V^\gamma$$

$$L_m: E_m^s \rightarrow E_{m+1}^s \leftarrow \text{contracting}$$

Def: $f: M \rightarrow M$ diffeomorphism is called Anosov diffeomorphism if the whole manifold M is an hyperbolic set.

Theorem: If $f: M \rightarrow M$ is a C^1 Anosov diffeomorphism then f is structurally stable

Sketch: $g \sim f$ C^1 -close

Then $g: M \rightarrow M$ is hyperbolic (follows from proposition)

$$\begin{array}{ccc} M & \xrightarrow{f} & M \\ h \downarrow & & \downarrow h \\ M & \xrightarrow{g} & M \end{array} \quad ?$$

Shadowing lemma (Lemat o ε trajektoriach):

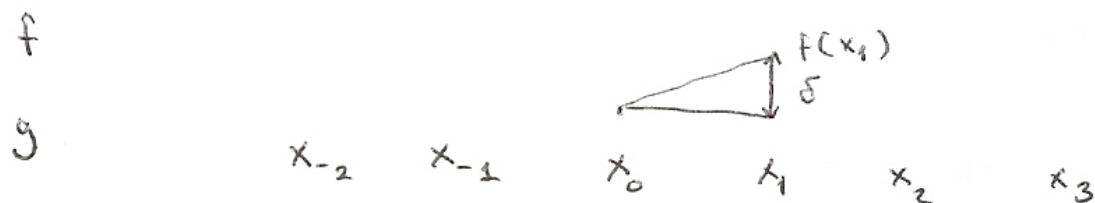
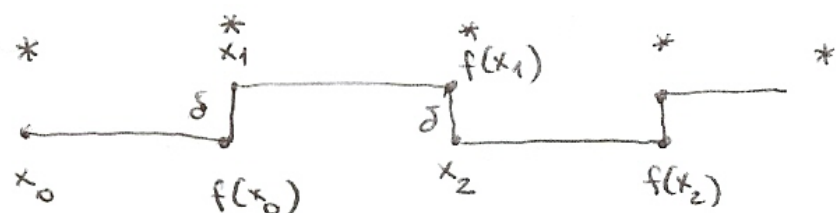
Def: A sequence $x_0, x_1, x_2, \dots, x_n, \dots$ is an ε trajectory if

$$d(x_{i+1}, f(x_i)) < \varepsilon.$$

Proposition: If f is an Anosov diffeomorphism then

(*) $\forall \varepsilon > 0 \exists \delta > 0$ such that every δ -trajectory can "be ε -shadowed" by a "real" trajectory. i.e.

$\exists y \in M$ such that $d(f^i y, x_i) < \varepsilon$.



trajectory of g is a δ -trajectory for f .

$h(x)$ = a unique y defined by (*)

Continuity of h . Suppose not. Then there exists a sequence

$x_k \rightarrow x$ s.t. $d(h(x_k), h(x)) \geq \delta_0 > 0$

Assume that $h(x_k) \rightarrow z \in M$

$$d(f^i h(x), f^i(z)) \leq d(f^i h(x), g^i(x)) + d(g^i(x), g^i(x_k)) + d(g^i(x_k), f^i h(x_k)) + d(f^i h(x_k), f^i(z)) < 4\varepsilon$$

$\downarrow \quad \downarrow \quad \downarrow \quad \downarrow$
 $0 \quad \quad \quad 0 \quad \quad \quad 0 \quad \quad \quad 0$

Conclusion: For all $i \in \mathbb{Z}$ $d(f^i h(x), f^i(z)) < 4\varepsilon$

$\Downarrow$
 $h(x) = z$